

Second unofficial exercise sheet on Quantum Gravity Winter term 2019/20

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Exercise 4: Relativistic charged particle as a regular system

Consider a charged massive point particle in special relativity of $(d + 1)$ -dimensions, described by [1, sec. 16]

$$S[x^i] = \int_{t_A}^{t_B} dt L(x^i, \dot{x}^i) := \int_{t_A}^{t_B} dt \left\{ -m\sqrt{1 - \delta_{ij}\dot{x}^i\dot{x}^j} - q\Phi(x^j) + q\dot{x}^j A_i(x^k) \right\}, \quad i, j, k = 1, \dots, d, \quad (1)$$

where $\dot{x}^i := dx^i/dt$, m and q are the mass and electric charge, Φ and A_i the electric and vector potentials.

1. Show that the *canonical* d -momentum reads

$$P_i = P_i(x^j, \dot{x}^k) := \frac{\partial L}{\partial \dot{x}^i} = \delta_{ij} \frac{m\dot{x}^j}{\sqrt{1 - \delta_{kl}\dot{x}^k\dot{x}^l}} + qA_i. \quad (2)$$

2. Show that the following partial inverse reads

$$\dot{x}^i = \bar{v}^i(x^j, P_k) = \delta^{ij} \frac{P_j - qA_j}{\sqrt{m^2 + \delta^{kl}(P_k - qA_k)(P_l - qA_l)}}. \quad (3)$$

Remark. Such a partial inverse exists because the Hessian $M_{ij} := \frac{\partial P_i}{\partial \dot{x}^j} \equiv \frac{\partial^2 L}{\partial \dot{x}^j \partial \dot{x}^i}$ is a *regular* matrix, which is a condition for the *implicit function theorem* [2]; the system is *regular* because M_{ij} is regular.

3. Show that the canonical Hamiltonian of the particle reads

$$H^c = H^c(x^i, P_j) = \left\{ \dot{x}^i P_i - L(x^i, \dot{x}^j) \right\}_{\dot{x}^i = \bar{v}^i(x^j, P_k)} = \sqrt{m^2 + \delta^{kl}(P_k - qA_k)(P_l - qA_l)} + q\Phi. \quad (4)$$

4. Derive the Hamilton's equations of motion in terms of Poisson brackets [3, sec. 42]

$$\frac{d\omega}{dt} = [\omega, H]_P, \quad \text{where } \omega = x^i, P_j, \quad [f, g]_P := \frac{\partial f}{\partial x^i} \frac{\partial g}{\partial P_i} - \frac{\partial g}{\partial x^i} \frac{\partial f}{\partial P_i}. \quad (5)$$

Why are the equations for \dot{x}^i less interesting than those for \dot{P}_i ?

Exercise 5: Relativistic particle as a singular system: Lagrangian formalism

It is an experimental fact that a physical system obeys the *Newton's principle of determinacy* [4, sec. 1.1]:

The initial state of a mechanical system (the totality of positions and velocities of its points at some moment of time) uniquely determines all of its motion.

In other words, for a mechanical system with s generalised coordinates $\{q^i\}$, an initial data $(q_0^i; \dot{q}_0^i; t_0)$ of $(2s + 1)$ quantities uniquely determines the evolution of the system. We will show that the action for a point particle in eq. (6), as a singular system, *violates* this principle.

Consider a massive point particle in special relativity in $(1 + 1)$ -dimensions, described by the action

$$S[t, x] = \int_{\lambda_A}^{\lambda_B} d\lambda L(x^\mu, \dot{x}^\nu) := \int_{\lambda_A}^{\lambda_B} d\lambda \left\{ -m\sqrt{\dot{t}^2 - \dot{x}^2} \right\}, \quad (6)$$

where $\dot{x}^\mu := dx^\mu/d\lambda$. The system is *singular* because $M_{\mu\nu} := \frac{\partial^2 L}{\partial \dot{x}^\nu \partial \dot{x}^\mu}$ is singular.

1. Since $\{x^\mu\}$ are cyclic [3, sec. 14], the corresponding generalised momenta are integrals of motion and can serve as the velocity initial data. Show that these constants of motion can be chosen to be

$$E := \frac{m\dot{t}}{\sqrt{\dot{t}^2 - \dot{x}^2}}, \quad p := \frac{m\dot{x}}{\sqrt{\dot{t}^2 - \dot{x}^2}}. \quad (7)$$

For simplicity, we assume in the following $E > 0$.

2. It is easy to check that (E, p) satisfies the relation

$$E = \sqrt{p^2 + m^2} > 0. \quad (8)$$

We could use β and $\sigma(\lambda)$ to recognise this, which are defined as

$$\sinh \beta := \frac{p}{m}, \quad \sigma(\lambda) := \sqrt{\dot{t}^2 - \dot{x}^2} > 0. \quad (9)$$

Show that eq. (7) can be integrated as

$$t(\lambda) - t_0 = \cosh(\beta) \int_{\lambda_a}^{\lambda} d\kappa \sigma(\kappa), \quad x(\lambda) - x_0 = \sinh(\beta) \int_{\lambda_a}^{\lambda} d\kappa \sigma(\kappa). \quad (10)$$

Remark 1. The initial data $(t_0, x_0; \beta; \lambda_0)$ of 4 quantities, which is less than the expected number of 5, is sufficient for the evolution of the system, and the initial data (E, p) cannot be arbitrarily chosen. This is a basic feature of all constrained systems in the Lagrangian formalism.

Remark 2. The evolution of the system is not uniquely determined: eq. (10) contains a functional indeterminacy $\sigma(\lambda)$. This is another feature for gauge systems.

Remark 3. The word gauge here is in a more general sense than it is in Yang(楊)–Mills theories!

3. In physics, one chooses $\sigma(\lambda) = \sigma \equiv \text{const.}$ for definiteness; in particular, $\sigma = 1$ makes λ the proper time. This is an example of ‘gauge fixing’, which can already be imposed in eq. (7).

What happens if one fixes the gauge earlier, i.e. in eq. (6)?

Exercise 6: Relativistic charged particle as a singular system: vanishing Hamiltonian

Consider a charged massive point particle in special relativity of $(d + 1)$ -dimensions, described by the action

$$S[x^\mu] = \int_{\lambda_A}^{\lambda_B} d\lambda L(x^\mu, \dot{x}^\nu) := \int_{\lambda_A}^{\lambda_B} d\lambda \left\{ -m\sqrt{-\eta_{\mu\nu}\dot{x}^\mu\dot{x}^\nu} + q\dot{x}^\mu A_\mu \right\}, \quad (11)$$

where $\dot{x}^\mu := dx^\mu/d\lambda$, A_μ is the four-potential.

1. Show that the action is invariant under a non-degenerate reparametrisation of the integral variable

$$\lambda \mapsto \lambda_f = f(\lambda), \quad f'(\lambda) > 0. \quad (12)$$

As a weaker consequence, $L(x^\mu, \dot{x}^\nu)$ is a homogeneous function of degree 1 with respect to \dot{x}^ν [5],

$$L(x^\mu, k\dot{x}^\nu) = kL(x^\mu, \dot{x}^\nu), \quad k > 0. \quad (13)$$

2. Show that the canonical $(d + 1)$ -momentum reads

$$P_\mu = P_\mu(x^\nu, \dot{x}^\rho) := \frac{\partial L}{\partial \dot{x}^\mu} = \eta_{\mu\nu} \frac{m\dot{x}^\nu}{\sqrt{-\eta_{\xi\pi}\dot{x}^\xi\dot{x}^\pi}} + qA_\mu. \quad (14)$$

3. Show that

$$M_{\mu\nu} := \frac{\partial P_\mu}{\partial \dot{x}^\nu} \equiv \frac{\partial^2 L}{\partial \dot{x}^\nu \partial \dot{x}^\mu} = \frac{-\eta_{\mu\nu}\eta_{\xi\pi} + \eta_{\mu\xi}\eta_{\nu\pi}}{\sqrt{-\eta_{\rho\sigma}\dot{x}^\rho\dot{x}^\sigma}} \dot{x}^\xi\dot{x}^\pi; \quad (15a)$$

$$M_{\mu\nu}\dot{x}^\nu = 0. \quad (15b)$$

Furthermore, use the implicit function theorem to argue that the partial inverse $\dot{x}^\mu = \bar{v}^\mu(x^\nu, P_\xi)$ does not exist.

Remark. The system is singular because the Hessian $M_{\mu\nu}$ is singular, which has just been proven.

4. Show that

$$\dot{x}^\mu P_\mu(x^\nu, \dot{x}^\rho) - L(x^\mu, \dot{x}^\nu) = 0. \quad (16)$$

This holds for all systems, that has a Lagrangian $L(q^i, \dot{q}^j)$ homogeneous of degree 1 with respect to the generalised velocities \dot{q}^i [6, sec. 3.1.1], which is left as an exercise.

Since the Hamiltonian-to-be vanishes, it seems that there is no way to understand the dynamics of the system in the Hamiltonian approach. In the following we will follow [7, ch. 2] and find a way around. More popular references include [8].

Exercise 7: Extended analytical mechanics with velocity: kinematics

Consider a time-independent mechanical system described by the *Lagrangian action*

$$S^l[q^i] = \int_{t_A}^{t_B} dt L(q^i, \dot{q}^i), \quad i = 1, \dots, s > 1. \quad (17)$$

The system is called *regular (singular)* if $M_{ij} := \frac{\partial^2 L}{\partial \dot{x}^j \partial \dot{x}^i}$ is regular (singular). Define the following *Lagrangian, Hamiltonian* and *action with velocity*

$$S^v[q^i, p_j, v^k] = \int_{t_A}^{t_B} dt \left\{ L^v + p_i (\dot{q}^i - v^i) \right\}, \quad L^v := L(q^i, v^j); \quad (18a)$$

$$= \int_{t_A}^{t_B} dt \left\{ p_i \dot{q}^i - H^v \right\}, \quad H^v = H^v(q^i, p_k, v^l) := p_i v^i - L^v. \quad (18b)$$

1. Apply the variational principle for $\{p_i\}$ to the integral in eq. (18a) and show that it leads to eq. (17).
2. Apply the variational principle for $\{q^i, p_j, v^k\}$ to the integral in eq. (18b) and show that

$$\dot{\omega} = [\omega, H^v]_P, \quad \omega = q^i, p_j, \quad [g, h]_P := \frac{\partial g}{\partial q^i} \frac{\partial h}{\partial p_i} - \frac{\partial h}{\partial q^i} \frac{\partial g}{\partial p_i}; \quad (19a)$$

$$0 = \frac{\partial H^v}{\partial v^i} \equiv p_i - \frac{\partial L^v}{\partial v^i}. \quad (19b)$$

3. For a regular system, eq. (19b) can be partially inverted to $v^i = \bar{v}^i(q^j, p_k)$. Show that the integral in eq. (18b) leads to the *Hamiltonian action*

$$S^h[q^i, p_j] = \int_{t_A}^{t_B} dt \left\{ p_i \dot{q}^i - H^c \right\}, \quad H^c = H^c(q^i, p_j) := H^v|_{v^i=\bar{v}^i(q^j, p_k)} \equiv \left(p_i \dot{q}^i - L \right)|_{\dot{q}^i=\bar{v}^i(q^j, p_k)}. \quad (20)$$

Do the Hamilton's equations follow from this action?

4. For a singular system, rank $M_{ij} = r < s$. One can expect that there are $(s - r)$ velocities, $\{v^u\}$, that *cannot* be solved from eq. (19b) and are *inexpressible* in terms of $(q^i, p_i; v^i)$, whereas r velocities, $\{v^e\}$, *can* be solved and are *expressible* in terms of $(q^i, p_i; v^i)$.

(Optional) Argue that the assert above can be more accurate such that

$$v^e = \bar{v}^e(q^i, p_e; v^u), \quad (21)$$

i.e. the expressible velocities are *independent* of $\{p_u; v^e\}$, where $\{p_u\}$ are the conjugate momenta of the generalised coordinates corresponding to the inexpressible velocities, and $\{v^e\}$ the expressible velocities.

5. Inserting eq. (21) into H^v yields the *Hamiltonian with primary constraint*

$$H^P = H^S(q^i, p_e) + v^u F_u, \quad F_u = F_u(q^i, p_i) = p_u - f_u(q^i, p_e). \quad (22)$$

$\{F_u\}$ are called *primary constraints* [9, 10], which are *linear* in the canonical momenta p_u in our formalism.

(Optional) Derive eq. (22).

Remark 1. The primary constraints originate from the definition of momenta and contain therefore no knowledge concerning the *dynamics* of the system.

Remark 2. Because of the constraints (in general, $\{\Phi_a\}$), motions are confined in the submanifold $\Phi_a = 0$ in the phase space. This is a character for *all constrained systems* in the Hamilton's approach.

Exercise 8: *Linear action for a massive relativistic particle: primary constraints*

Consider a charged massive point particle in special relativity, described by the Lagrangian action

$$S^l[x^\mu] = \int_{\lambda_A}^{\lambda_B} d\lambda L(x^\mu, \dot{x}^\nu) := \int_{\lambda_A}^{\lambda_B} d\lambda \left\{ -m\sqrt{-\eta_{\mu\nu}\dot{x}^\mu\dot{x}^\nu} + q\dot{x}^\mu A_\mu \right\}, \quad m > 0. \quad (23)$$

1. Show that the Hamiltonian with velocity reads

$$H^v = m\sqrt{-\eta_{\mu\nu}v^\mu v^\nu} + v^\nu (P_\nu - qA_\nu). \quad (24)$$

2. Take v^0 as the inexpressible velocity. Show that the rest of the velocities, $\{v^i\}$, are expressible such that

$$v^i = \bar{v}^i(x^\mu, P_i; v^0) = \delta^{ij} \frac{P_j - qA_j}{\sqrt{m^2 + \delta^{kl}(P_k - qA_k)(P_l - qA_l)}} v^0. \quad (25)$$

3. Insert eq. (25) into S^v and show that

$$S^p[x^\mu, P_\nu; v^0] := S^v[x^\mu, P_\nu; v^0, v^i = \bar{v}^i(x^\mu, P_i; v^0)] = \int_{\lambda_A}^{\lambda_B} d\lambda \{P_\mu \dot{x}^\mu - H^p\}, \quad (26a)$$

$$H^p = H^p(x^\mu, P_\mu; v^0) = v^0 F_0, \quad (26b)$$

$$F_0 = P_0 - f_0(x^\mu, P_i), \quad f_0 = qA_0 - \sqrt{m^2 + \delta^{kl}(P_k - qA_k)(P_l - qA_l)}. \quad (26c)$$

Exercise 9: *Quadratic action for a relativistic particle: secondary constraints*

The evolution of a phase-space function $g(q^i, p_j)$ is determined by $\dot{g} = [g, H^p]_p$. Consistency requires that a constrain Φ persists in time, so that

$$0 \equiv \dot{\Phi} = [\Phi, H^p]_p = [\Phi, H^s]_p + v^\mu [\Phi, F_\mu]_p, \quad (27)$$

New generations of constraints can be produced in this way, which are collectively called *secondary constraints*. Moreover, a Lie algebra of constraints $[\Phi_a, \Phi_b]_p$ emerges. If the algebra closes,

$$[\Phi_a, \Phi_b]_p = C_{ab}^c \Phi_c, \quad (28)$$

the constraints and the system are called *first-class* [9].

Consider a charged point particle in special relativity, described by the Lagrangian action [11, sec. 2.1]

$$S^l[x^\mu, N] = \int d\lambda \frac{N}{2} \left\{ \eta_{\mu\nu} \frac{\dot{x}^\mu \dot{x}^\nu}{N} - m^2 + q \frac{\dot{x}^\mu}{N} A_\mu \right\}, \quad N = N(t) > 0, \quad m \geq 0. \quad (29)$$

1. Derive the Euler–Lagrange equation for N . Furthermore, solve this equation for N and show that eq. (29) gives eq. (23) for $m > 0$.
2. Show that the Hamiltonian with velocity reads

$$H^v = \frac{N}{2} \left(-\eta_{\mu\nu} \frac{v^\mu v^\nu}{N} + m^2 - q \frac{v^\mu}{N} A_\mu \right) + v^\nu P_\nu + v^N P_N. \quad (30)$$

3. Show that the Hamiltonian with primary constraints reads

$$H^p = H^s + v^N F_N =: -NH_\perp + v^N F_N, \quad (31a)$$

$$H_\perp = -\frac{1}{2} \left(\eta^{\mu\nu} (P_\mu - qA_\mu)(P_\nu - qA_\nu) + m^2 \right), \quad F_N = P_N, \quad (31b)$$

4. Show that H_\perp is a secondary constraint. Furthermore, show that there are no further constraints, and the system is first-class.

Remark 1. The secondary constraint is already contained in H^s in this example.

Remark 2. Confusingly, H_\perp is often called the *Hamiltonian constraint* in the literature.

5. In this case, the Dirac quantisation rules for first-class systems [6, sec. 3.1.2] read

$$\hat{F}_N \Psi = 0, \quad \hat{H}_\perp \Psi = 0. \quad (32)$$

Because H^P consists of constraints only and the canonical Hamiltonian H^c vanishes, there is no Schrödinger-type of equation. Consequently, *there is no time* in the equations.

Show that eq. (32) leads to the Klein–Gordon equation

$$\eta^{\mu\nu} (\hbar\partial_\mu - iqA_\mu)(\hbar\partial_\nu - iqA_\nu)\psi - m^2\psi = 0, \quad \psi = \psi(x^\mu). \quad (33)$$

In particular, the dependence of N drops out.

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