

The "single step" constraint implies that size  $(i, j)$  can be filled only after sizes  $(i-1, j)$  and  $(i, j-1)$ :

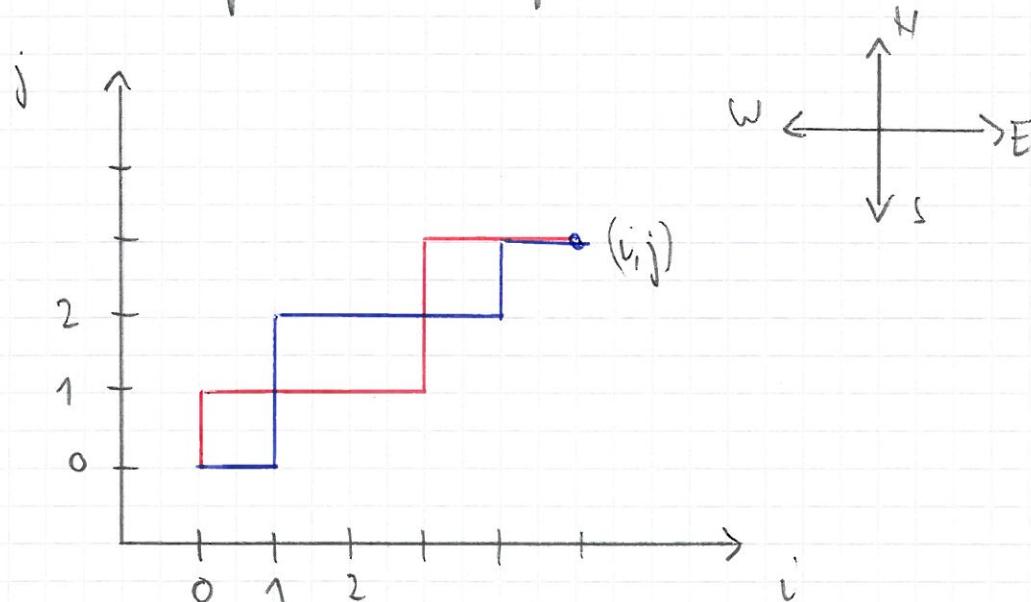
$$\textcircled{X} \quad t(i, j) = \max [t(i-1, j), t(i, j-1)] + \tau_{ij}$$

where the  $\tau_{ij}$  are exponentially distributed random waiting times with  $\langle \tau_{ij} \rangle = 1$

At the boundaries ( $i=1, j=1$ ) we have instead

$$\begin{aligned} t(i, 1) &= t(i-1, 1) + \tau_{i,1} \\ t(1, j) &= t(1, j-1) + \tau_{1,j} \end{aligned} \quad \left. \right\}$$

To formulate a solution to  $\textcircled{X}$  we introduce the set of north-east directed paths  $w$  from the origin to  $(i, j)$ :



- length of paths  $i+j$  }
- number of paths  $\binom{i+j}{i}$  }

To each path  $\omega$  we associate the waiting time

$$t(\omega) = \sum_{(i,j) \in \omega} \tau_{ij}$$

then the  $t(i,j)$  are given by

$$t(i,j) = \min_{\substack{\omega \text{ ending} \\ \text{at } (i,j)}} (t(\omega))$$

Proof: By iteration.

Remarks:

- In mathematics this problem is known as last passage percolation.
- Defining "site energies"  $\varepsilon_{ij} = -\tau_{ij}$ , and "path energies"  $E(\omega) = -t(\omega)$

then  $E(i,j)$  is the ground state energy of a directed polymer moving in the random medium defined by the  $\varepsilon_{ij}$ :

$$E(i,j) = \min_{\substack{\omega \text{ ending} \\ \text{at } (i,j)}} \left[ \sum_{(i,j) \in \omega} \varepsilon_{ij} \right]$$

"DPRM" (Kardar, Zhang 1987)

- The DPRM is a problem of extreme value theory for highly correlated random variables.

Example: Consider paths along the diagonal,  
 $(i, j) = (n, n)$

$$\Rightarrow \underline{\langle E(\omega) \rangle = -2n}$$

On the other hand we know from hydrodynamics that the growth speed along the diagonal is

$$V(0) = \frac{1}{2} \Rightarrow \begin{matrix} \text{height } h \text{ is reached} \\ \text{at time } t = 2h \end{matrix} \}$$

and since  $h = 2n$  we have

$$\underline{E(n, n) = \min_{\omega} \{E(\omega)\} = -4n = 2\langle E \rangle}$$

Problems: - Compare to i.i.d. statistics  
- Compare ground state energy or  
 fct. of path direction }

- The same approach can be applied to the dTASEP. In this case the waiting times  $\tau_{ij}$  are integer valued with a geometric distribution:

$$\underline{P(\tau) = \pi (1-\pi)^{\tau-1}, \quad \tau > 1}$$

## 6° Fluctuation theory

Goal: Develop a theory for density fluctuations  
three levels      ~ the ASEP height fluctuations (roughness) ~ the single step model.

Idea: Lagrangian approach: hydrodynamics + noise.

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### a) Linear density fluctuations

Recall: The hydrodynamic equation for the symmetric exclusion process is linear diffusion

$$\frac{\partial \bar{g}}{\partial t} = -\nu \frac{\partial^2 \bar{g}}{\partial x^2}, \quad \nu = \frac{1}{2} \Gamma_0 a^2$$


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We consider fluctuations  $\phi$  around a homogeneous density  $\bar{g}$ :  $g(x,t) = \bar{g} + \phi(x,t)$

$$\Rightarrow \frac{\partial \phi}{\partial t} = -\nu \frac{\partial^2 \phi}{\partial x^2} - \frac{\partial}{\partial x} \xi(x,t) \quad (\text{red circle})$$


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where  $\xi(x,t)$  is a fluctuating current modeled as white noise in space and time

$$\langle \xi(x,t) \rangle = 0, \quad \langle \xi(x,t) \xi(x',t') \rangle = D \delta(x-x') \delta(t-t')$$


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D: noise strength (not diffusion coefficient)

Remark: White noise is always to be understood as a limit of a correlated process:

$$\langle \xi(x,t) \xi(x',t') \rangle = a_x^{-1} a_t^{-1} \left\{ e\left(\frac{x-x'}{a_x}, \frac{t-t'}{a_t}\right) \right\}$$

$\downarrow a_x, a_t \rightarrow 0$

$$D \delta(x-x') \delta(t-t')$$

To solve  $\star$  we introduce spatial Fourier transforms:

$$\begin{aligned} \hat{\phi}(k,t) &= \int dx e^{ikx} \phi(x,t) \\ \hat{\xi}(k,t) &= \int dx e^{ikx} \xi(x,t) \end{aligned} \quad \left. \right\}$$

$$\Rightarrow \frac{\partial}{\partial t} \hat{\phi}(k,t) = -\sqrt{k^2} \hat{\phi}(k,t) + ik \hat{\xi}(k,t)$$


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Ornstein-Uhlenbeck process with friction  $\sqrt{k^2}$  and force  $ik \hat{\xi}(k,t)$ .

Solution:

$$\begin{aligned} \hat{\phi}(k,t) &= e^{-\sqrt{k^2}t} \hat{\phi}(k,0) + \\ &+ ik \int_0^t ds e^{-\sqrt{k^2}(t-s)} \hat{\xi}(k,s) \end{aligned}$$

For simplicity we set  $\hat{\phi}(k,0) = 0$ .

$$\Rightarrow \langle \hat{\phi}(k, t) \hat{\phi}(k', t') \rangle =$$

$$= -kk' \int_0^t ds \int_0^{t'} ds' e^{-\sqrt{k^2(t-s)}} e^{-\sqrt{k'^2(t'-s')}} \times$$

$$\times \langle \hat{s}(k, s) \hat{s}(k', s') \rangle$$

$$\text{Now } \langle \hat{s}(k, t) \hat{s}(k', t') \rangle =$$

$$= \int dx \int dx' e^{ikx} e^{ik'x'} \underbrace{\langle s(x, t) s(x', t') \rangle}_{= D \delta(x-x') \delta(t-t')} = 2\pi D \delta(t-t') \delta(k+k')$$

$$= D \delta(t-t') \int dx e^{i(k+k')x} \underbrace{= 2\pi \delta(k+k')}$$

$$\Rightarrow \langle \hat{\phi}(k, t) \hat{\phi}(k', t') \rangle =$$

$$= 2\pi D k^2 \delta(k+k') \int_0^t ds \int_0^{t'} ds' e^{-\sqrt{k^2(t+t'-s-s')}} \times \delta(s-s')$$

$$= 2\pi D k^2 \delta(k+k') e^{-\sqrt{k^2(t+t')}} \int_0^{\min(t, t')} ds e^{-2\sqrt{k^2}s}$$

Take  $t > t' \Rightarrow \min(t, t') = t'$

(65)

$$\Rightarrow \langle \hat{\phi}(k, t) \hat{\phi}(k', t') \rangle =$$

$$= 2\pi D k^2 \delta(k+k') e^{-\sqrt{k^2(t+t')}} \frac{1}{2\sqrt{k^2}} (e^{2\sqrt{k^2}t'} - 1)$$

$$= \pi \left( \frac{D}{\sqrt{k^2}} \right) \delta(k+k') \left( e^{-\sqrt{k^2}|t-t'|} - e^{-\sqrt{k^2}(t+t')} \right)$$

In the stationary state ( $t, t' \rightarrow \infty$ ) this reduces to

$$\langle \hat{\phi}(k, t) \hat{\phi}(k', t') \rangle = \pi \left( \frac{D}{\sqrt{k^2}} \right) \delta(k+k') e^{-\sqrt{k^2}|t-t'|}$$

$$\Rightarrow \langle \phi(x, t) \phi(x', t') \rangle =$$

$$= \frac{1}{4\pi} \frac{D}{\sqrt{k^2}} \int dk e^{-ik(x-x')} e^{-\sqrt{k^2}|t-t'|}$$

$$= \frac{1}{4\pi} \frac{D}{\sqrt{k^2}} \cdot \frac{1}{|t-t'|^{1/2}} e^{-\frac{(x-x')^2}{4\sqrt{|t-t'|}}}$$

$\Rightarrow$  density fluctuations are correlated on the scale of the diffusion length  $\sim \sqrt{|t-t'|}$ .

$$\underline{t \rightarrow t'} : \langle \phi(x, t) \phi(x', t') \rangle = \frac{D}{2\sqrt{k^2}} \delta(x-x')$$

which can be used to determine the noise strength  $D$ .

To this end consider the fluctuation in particle number in a region of size  $L$ :

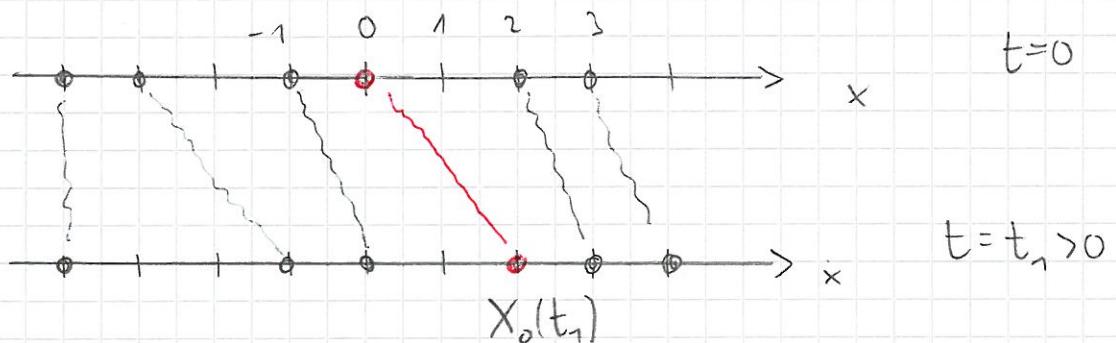
$$N = \int_0^L dx g(x,t) = \bar{g}L + \int_0^L dx \phi(x,t)$$

$$\Rightarrow \langle (N - \langle N \rangle)^2 \rangle = \int_0^L dx \int_0^L dx' \langle \phi(x,t) \phi(x',t) \rangle = \\ = \frac{D}{2v} \cdot L \stackrel{?}{=} g(1-g) \cdot L \Rightarrow \frac{D}{2v} = g(1-g)$$


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### b) Single file diffusion

Consider the motion of a tagged particle initially located at  $x=0$ :



$\Rightarrow$  up to corrections of  $O(1)$   $X_0(t)$  is given by the time-integrated particle current through the origin:

$$X_0(t) = \frac{1}{g} \int_0^t j(0,s) ds$$


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