

process where the rules depend
on the initial (rather than final) state
($\alpha = 0$).

(iii) Under the Itô interpretation the standard
rules of variable transformation do not
apply $\Rightarrow$ Itô calculus, stochastic integration

4° Diffusion in inhomogeneous media

- For non-interacting particles the positional
probability density $P_1(x,t)$ is equivalent to the
density $\rho(x,t)$ of a many-particle system

$\Rightarrow$ FP-eq can be interpreted as a diffusion
equation (here: in one spatial dimension)

- On the microscopic level diffusion processes
are governed by Fick's laws, which read
(for constant diffusion coefficient D):

(I) $\frac{\partial \rho}{\partial t} + \frac{\partial j}{\partial x} = 0$ particle number
conservation

(II) $j = -D \frac{\partial \rho}{\partial x}$

| How is (II) to be generalized when D depends
on position, $D = D(x)$?

Two obvious possibilities:

$$(i) \quad \underline{\dot{p} = -D(x) \frac{\partial p}{\partial x}}$$

$$(ii) \quad \underline{\dot{p} = -\frac{\partial}{\partial x} D(x) p}$$

Compare to the multiplicative Langevin equation with $A(x) = 0$:

$$\dot{x} = g(x) \xi(t) \quad \langle \xi(t) \xi(t') \rangle = \delta(t-t')$$

↓ "interpretation" α

$$\frac{\partial P_1}{\partial t} = -\frac{\partial}{\partial x} \alpha g' g P_1 + \frac{1}{2} \frac{\partial^2}{\partial x^2} g^2 P_1 =$$

$$= -\frac{\partial}{\partial x} \left[\alpha g' g P_1 - \frac{\partial}{\partial x} \left(\frac{1}{2} g^2 \right) P_1 \right] =$$

$$= -\frac{\partial}{\partial x} \left[(\alpha - 1) g' g P_1 - \frac{1}{2} g^2 \frac{\partial P_1}{\partial x} \right] =$$

$$= -\frac{\partial}{\partial x} \left[(\alpha - 1) D' P_1 - D \frac{\partial P_1}{\partial x} \right]$$

with $D(x) = \frac{1}{2} g(x)^2$.

We conclude that (i) corresponds to $\alpha = 1$,
and (ii) to $\alpha = 0$.

In the following we show that the choice of α

- has macroscopically observable consequences
- depends on the microscopic details of the process

a) Macroscopic behavior

Consider the general relation

$$j = - \left[(1-\alpha) D' f + D \frac{\partial f}{\partial x} \right]$$

for different special situations.

• stationary state: $j = 0 \Rightarrow \frac{df_s}{dx} = -(1-\alpha) \frac{D'}{D} f_s$

$$\Rightarrow \frac{1}{f_s} \frac{df_s}{dx} = -(1-\alpha) \frac{D'}{D}, \quad \frac{d}{dx} \ln f = -(1-\alpha) \frac{d}{dx} \ln D$$

$$\Rightarrow \underline{f_s(x) = C D(x)^{-(1-\alpha)}}$$

$\alpha = 1$: $f_s = \text{const.}$

$\alpha < 1$: Particles accumulate in regions where $D(x)$ is small.

• homogeneous density: $f = \text{const.} = f_0$

$$\Rightarrow \underline{j = -(1-\alpha) D' f_0}$$

$\alpha = 1$: No current

$\alpha < 1$: Current, towards regions where $D(x)$ is small.

• particle drift: Consider the positional probability density $P_1(x, t)$ of a particle with a localized

initial condition. The position of the particle at time t is the

$$\langle x \rangle = \int dx \, x P_1(x, t)$$

$$\Rightarrow \underline{\frac{d}{dt} \langle x \rangle} = \int dx \, x \frac{\partial P_1}{\partial t} = - \int dx \, x \frac{\partial}{\partial x} J$$

$$= - \int dx \left[(1-\alpha) D' P_1 + D \frac{\partial P_1}{\partial x} \right] =$$

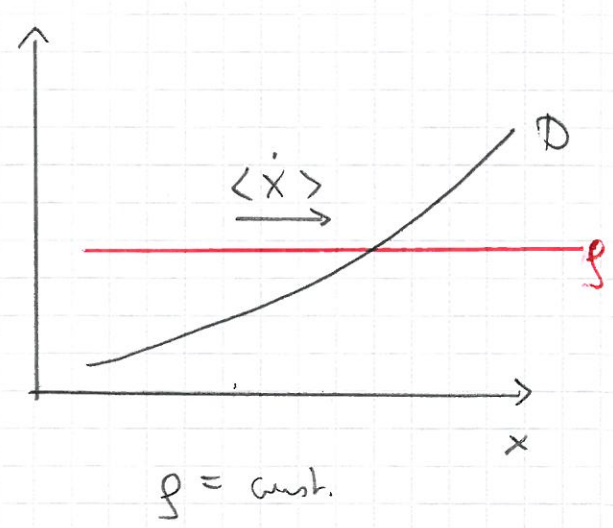
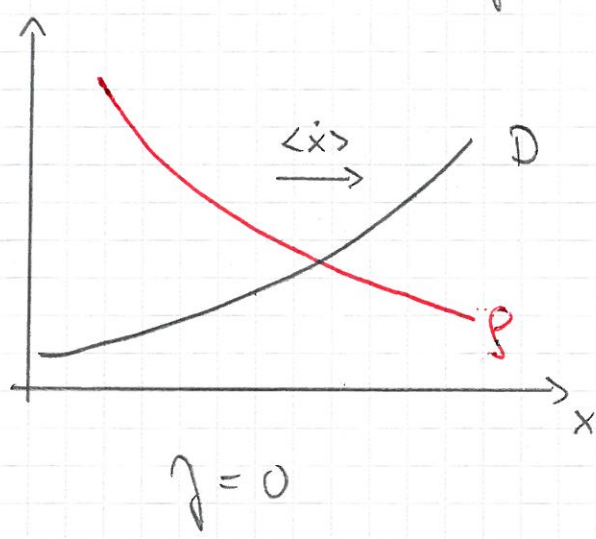
$$= \int dx \left(\alpha D' P_1 - \frac{\partial}{\partial x} D P_1 \right) = \alpha \int dx D' P_1$$

$$\approx \underline{\alpha D'(\langle x \rangle)} \text{ if } D(x) \text{ is slowly varying.}$$

$\alpha = 0$: No drift

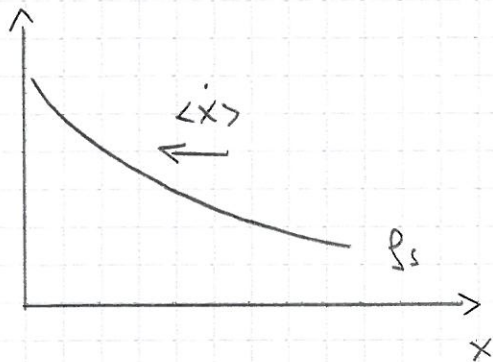
$\alpha > 0$: Drift towards regions where $D(x)$ is large

This implies "drift without flux" is the stationary case and "drift against the flux" is the case of homogeneous density



Analogy: Diffusion in an external force field (e.g., gravity)

$$\dot{x} = -F + \xi(t) \Rightarrow \left. \begin{aligned} \langle \dot{x} \rangle &= -F \\ \rho_s(x) &\sim e^{-Fx} \end{aligned} \right\}$$



$\Rightarrow$ density gradient compensates the drift such that $J=0$ in the stationary state.

b) Microscopic model (Langendoorn et al., 2001)

Consider a random walk in discrete time and continuous one-dimensional space.

- Jumps occur at discrete times $t_n = n \cdot \Delta t$ with equal probability to the left or right
- Jump length depends on position through

$$\underbrace{x(t + \Delta t) - x(t)}_{\Delta x} = \pm \sqrt{2 \tilde{D}(x(t), \Delta x) \cdot \Delta t} \quad \left. \vphantom{\frac{x(t + \Delta t) - x(t)}{\Delta x}} \right\}$$

$$\tilde{D}(x, \Delta x) = D(x \pm \alpha \Delta x)$$

- $\alpha = 0$: D evaluated at initial position
- $\alpha = 1$: D evaluated at final position

(i) Particle drift: If $D(x)$ is slowly varying

$$D(x + \alpha \Delta x) \approx D(x) + \alpha \Delta x D'(x)$$

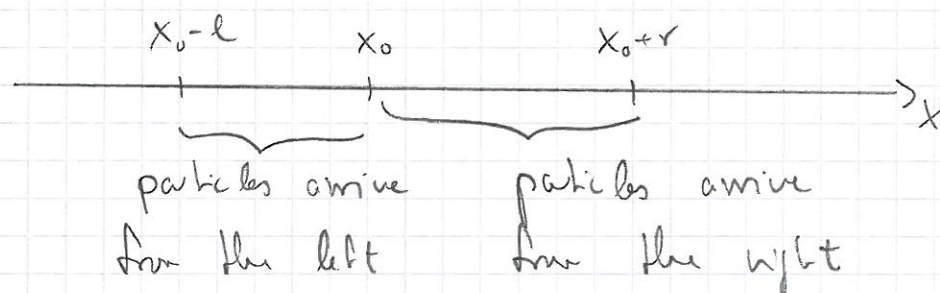
$$\Rightarrow (\Delta x)^2 = 2 D(x + \alpha \Delta x) \Delta t \approx$$

$$\approx 2 D(x) \Delta t + 2 D'(x) \alpha \Delta x \Delta t$$

$$\Rightarrow \Delta x = \alpha D'(x) \Delta t \pm \frac{1}{2} \sqrt{8 D \Delta t + 4 \alpha^2 D'^2 \Delta t^2}$$

$$\Rightarrow \underline{\Delta x = \alpha D'(x) \Delta t}$$

(ii) Particle current in a homogeneous system:



$$\Rightarrow \underline{j = \frac{1}{2} \rho (l-r)}$$

Particles jumping from x_0-l to x_0 satisfy

$$l = \sqrt{2 D(x_0-l + \alpha l) \Delta t}$$

$$\Rightarrow \underline{l^2} \approx 2 D(x_0) - 2 (1-\alpha) \underline{l} D'(x_0) \Delta t$$

$$\Rightarrow \left. \begin{aligned} l &\approx - (1-\alpha) D'(x_0) \Delta t + \sqrt{2 D(x_0) \Delta t} \\ r &= (1-\alpha) D'(x_0) \Delta t + \sqrt{2 D(x_0) \Delta t} \end{aligned} \right\}$$

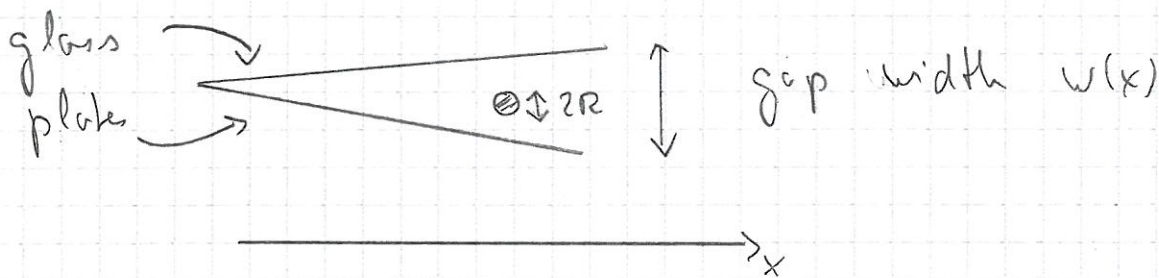
$$\Rightarrow \underline{\gamma = -\beta(1-\alpha) D'(x)}$$

in precise agreement with the microscope model.

c) Applications

(i) Brownian motion in confined geometry

(Lange et al., 2001)



Einstein relation: $D = \frac{k_B T}{6\pi\eta R}$

- glass plates increase friction

$$\Rightarrow \gamma(x) \text{ with } \gamma'(x) < 0$$

- thermal equilibrium $\Rightarrow T = \text{const.}$

$$\Rightarrow D' > 0 \quad \Rightarrow$$

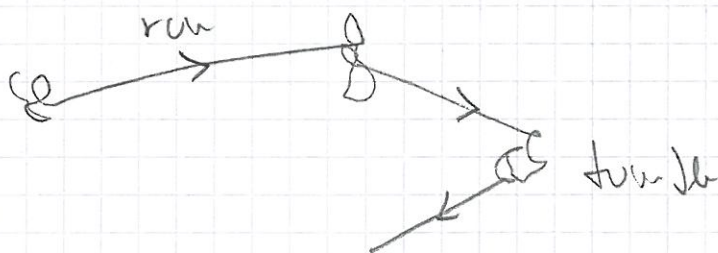
$$\beta_s = \text{const.} \Rightarrow \underline{\alpha = 1} \quad (\text{"isothermal"})$$

$$\Rightarrow \underline{\langle \dot{x} \rangle = \alpha D' > 0}$$

(ii) Chemotaxis of bacteria

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E. coli move by a sequence of straight runs and random tumbles:



- length of run $T_{run} \sim$ step length of RW

$$\Rightarrow \underline{D \sim T_{run}^2} \sim \frac{1}{\text{tumbling rate}^2}$$

- T_{run} depends on nutrient concentration

$\Rightarrow$ how to adjust this dependence in order to move towards increasing nutrient concentration?

- Bacterial drift $\langle \dot{x} \rangle = \alpha D'$

$\Rightarrow D$ and T_{run} should increase, tumbling rate decrease with nutrient concentration

- Mechanism works only if $\alpha > 0$

$\Rightarrow$ evaluating nutrient concentration at one position is not sufficient.

5° Fokker-Planck & Schrödinger operators

Fokker-Planck operator for systems with additive noise:

$$\mathcal{L} = - \frac{\partial}{\partial y} f(y) + \frac{1}{2} A \frac{\partial^2}{\partial y^2}$$

$\Rightarrow$ stationary distribution

$$\left. \begin{aligned} P_s(y) &= C e^{-\frac{2}{A} V(y)}, \quad V(y) = - \int_0^y dy' f(y') \\ &= \underline{C e^{-\Phi(y)}} \end{aligned} \right\}$$

P_s is a right eigenfunction of $\mathcal{L}$ with eigenvalue 0.

What can we say about other eigenfunctions?

a) Eigenfunction expansion of the FP-operator

Goal: Transform $\mathcal{L}$ into a symmetric ("Hermitian") differential operator.

To this end we note that, for any ϕ ,

$$\frac{1}{2} A \frac{\partial}{\partial y} e^{-\Phi} \frac{\partial}{\partial y} e^{\Phi} \phi(y) =$$

$$= \frac{1}{2} A \frac{\partial}{\partial y} \left\{ \Phi' + \frac{\partial}{\partial y} \right\} \phi(y) =$$

$$= \frac{1}{2} A \frac{\partial}{\partial y} \left\{ -\frac{2}{A} f(y) + \frac{\partial}{\partial y} \right\} \phi(y) = \mathcal{L} \phi(y)$$

$$\Rightarrow \underline{\mathcal{L} = \frac{1}{2} A \frac{\partial}{\partial y} e^{-\Phi} \frac{\partial}{\partial y} e^{\Phi}}$$

Now introduce the (symmetrized) operator

$$\begin{aligned} \tilde{\mathcal{L}} &:= e^{\Phi/2} \mathcal{L} e^{-\Phi/2} = \\ &= \frac{1}{2} A e^{\Phi/2} \frac{\partial}{\partial y} e^{-\Phi} \frac{\partial}{\partial y} e^{\Phi/2} \end{aligned}$$

which we claim is symmetric with respect to the standard scalar product:

$$\underline{\frac{2}{A} \langle \phi_n | \tilde{\mathcal{L}} \psi \rangle = \frac{2}{A} \int dy \phi(y) \tilde{\mathcal{L}} \psi(y) =}$$

$$= \int dy \underbrace{\phi(y) e^{\Phi/2}}_{\tilde{\phi}(y)} \frac{\partial}{\partial y} e^{-\Phi} \frac{\partial}{\partial y} \underbrace{e^{\Phi/2} \psi(y)}_{\tilde{\psi}(y)} = (\text{part. int.})$$

$$= - \int dy e^{-\Phi} \left(\frac{\partial}{\partial y} \tilde{\phi} \right) \left(\frac{\partial}{\partial y} \tilde{\psi} \right) = (\text{part. int.})$$

$$= \int dy \tilde{\psi} \frac{\partial}{\partial y} e^{-\Phi} \frac{\partial}{\partial y} \tilde{\phi} = \underline{\frac{2}{A} \langle \psi | \tilde{\mathcal{L}} \phi \rangle} \quad \square$$

It follows that $\tilde{\mathcal{L}}$ has orthogonal eigenfunctions ψ_n with real eigenvalues λ_n :

$$\tilde{\mathcal{L}} \psi_n = \lambda_n \psi_n, \quad \langle \psi_n | \psi_m \rangle = \delta_{nm}.$$

from which eigenfunctions of $\mathcal{L}$ can be constructed:

$$\mathcal{L}(\underbrace{e^{-\Phi/2}}_{\phi_n} \psi_n) = e^{-\Phi/2} \tilde{\mathcal{L}} \psi_n = \lambda_n \underbrace{e^{-\Phi/2}}_{\phi_n} \psi_n$$

In particular, the stationary distribution $\phi_0 \sim e^{-\Phi}$ corresponds to the "ground state" $\psi_0 \sim e^{-\Phi/2}$ with eigenvalue $\lambda_0 = 0$.

We next show that all eigenvalues are negative or zero:

$$\begin{aligned} \lambda_n &= \int dy \psi_n \tilde{\mathcal{L}} \psi_n = \int dy e^{\Phi/2} \phi_n e^{\Phi/2} \mathcal{L} \phi_n \\ &= \frac{1}{2} A \int dy e^{\Phi} \phi_n \frac{\partial}{\partial y} e^{-\Phi} \frac{\partial}{\partial y} e^{\Phi} \phi_n = \text{(p.i.)} \\ &= -\frac{1}{2} A \int dy e^{-\Phi} \left(\frac{\partial}{\partial y} e^{-\Phi} \phi_n \right)^2 \leq 0. \\ \Rightarrow \underline{0 = \lambda_0 \gg \lambda_1 \gg \lambda_2 \gg \dots} \end{aligned}$$

Provided $\lambda_1 < 0$, the convergence of an arbitrary initial condition to the stationary distribution occurs at rate λ_1 :

$$P_1(y, t) = \sum_n c_n \phi_n(y) e^{-\lambda_n t} \longrightarrow c_0 \phi_0(y)$$

b) Mapping to a Schrödinger problem

Consider the application of $\tilde{\mathcal{L}}$ to a function ϕ ,

$$\begin{aligned}
 \frac{2}{A} \tilde{\mathcal{L}} \phi &= e^{\Phi/2} \frac{\partial}{\partial y} e^{-\Phi} \frac{\partial}{\partial y} e^{\Phi/2} \phi = \\
 &= e^{\Phi/2} \frac{\partial}{\partial y} e^{-\Phi/2} \left(\frac{1}{2} \Phi' \phi + \phi' \right) = \\
 &= \cancel{e^{\Phi/2}} \left\{ -\frac{\Phi'}{2} \left(\frac{1}{2} \Phi' \phi + \cancel{\phi'} \right) \cancel{e^{-\Phi/2}} + \right. \\
 &\quad \left. + \cancel{e^{-\Phi/2}} \left(\frac{1}{2} \Phi'' \phi + \frac{1}{2} \cancel{\Phi'} \phi' + \phi'' \right) \right\} \\
 &= \phi'' + \left(\frac{1}{2} \Phi'' - \frac{1}{4} (\Phi')^2 \right) \phi
 \end{aligned}$$

$\Rightarrow \tilde{\mathcal{L}} = -\mathcal{H}$ with the Schrödinger operator

$$\mathcal{H} = -\frac{A}{2} \frac{\partial^2}{\partial y^2} + V_s(y)$$

$$\begin{aligned}
 \underline{V_s(y)} &= \frac{1}{4} A \left[\frac{1}{2} (\Phi')^2 - \Phi'' \right] = \\
 &= \frac{1}{4} A \left[\frac{1}{2} \left(\frac{2}{A} f(y) \right)^2 + \frac{2}{A} f'(y) \right] = \\
 &= \underline{\frac{1}{2} \left(f(y)^2/A + f'(y) \right)}
 \end{aligned}$$