

d) Counting statistics for renewal processes

For a general stationary point process we may consider the RV

$$\left. \begin{array}{l} N_T = \text{number of events in a time} \\ \text{interval of length } T \end{array} \right\}$$

For independent events we know that N_T is Poisson distributed, in particular

$$\text{Var}(N_T) = \langle N_T^2 \rangle - \langle N_T \rangle^2 = \langle N_T \rangle = \rho T$$

As a measure of fluctuations relative to the independent case define the index of dispersion or Fano factor

$$I_T := \frac{\langle N_T^2 \rangle - \langle N_T \rangle^2}{\langle N_T \rangle}$$

- Under which conditions is $\lim_{T \rightarrow \infty} I_T = 1$ (Poisson) or $I_T < 1$ (sub-Poisson)?
- When is $I_T > 1$ (super-Poisson) or $I_T < 1$ (sub-Poisson)?

We answer these questions for a general renewal process with waiting time distribution $f_{\Delta}(t)$ which satisfies the CLT. The time T_n of the n th event

$$T_n = \sum_{i=1}^n t_i$$

is distributed according to

$$\textcircled{*} f_n(t) = \frac{1}{\sqrt{2\pi\sigma_{\Delta}^2 n}} \exp\left[-\frac{(t - \mu_{\Delta} n)^2}{2n\sigma_{\Delta}^2}\right], \quad n \rightarrow \infty$$

where μ_{Δ} and σ_{Δ} denote the mean and variance of the waiting time. For large n we have

$$T_n/n \rightarrow \mu_{\Delta} + O(1/\sqrt{n})$$

which also implies that

$$N_T/T \rightarrow \frac{1}{\mu_{\Delta}} + O(1/T^{1/2})$$

We can therefore derive the pdf $f_T(N)$ of N_T from $f_n(t)$ through a deterministic change of variables:

$$N_T \approx t_n / \mu_\Delta = \frac{dN_T}{dt_n} = \frac{1}{\mu_\Delta}$$

$$\Rightarrow f_T(N) = \frac{dt_n}{dN_T} f_n(t) = \quad \text{⊗}$$

$$= \mu_\Delta \cdot \frac{1}{[2\pi\sigma_\Delta^2(T/\mu_\Delta)]^{1/2}} \exp\left[-\frac{(N\mu_\Delta - T)^2}{2\sigma_\Delta^2(T/\mu_\Delta)}\right] =$$

$$= \frac{1}{[2\pi(\frac{\sigma_\Delta^2}{\mu_\Delta^3})T]^{1/2}} \exp\left[-\frac{(N - T/\mu_\Delta)^2}{2(\frac{\sigma_\Delta^2}{\mu_\Delta^3})T}\right]$$

$\Rightarrow H$ is Gaussian with mean $\langle N \rangle = T/\mu_\Delta$
and variance

$$\langle N^2 \rangle - \langle N \rangle^2 = \frac{\sigma_\Delta^2}{\mu_\Delta^3} T = \frac{\sigma_\Delta^2}{\mu_\Delta^2} \langle N \rangle$$

$$\Rightarrow \underline{I_T = \frac{\sigma_\Delta^2}{\mu_\Delta^2} = CV(\Delta)^2 \text{ for } T \rightarrow \infty}$$

$CV(\Delta) = \sigma_\Delta / \mu_\Delta$ is called the coefficient of variation of Δ . For the exponential

distribution $CV(\Delta) = 1$.

Examples: (i) Pareto: $f_{\Delta}(t) = \alpha(1+t)^{-(\alpha+1)}$, $t \geq 0$

has finite variance for $\alpha > 2$,

$$\text{Then } \mu_{\Delta} = \frac{1}{\alpha-1}, \quad \langle \Delta^2 \rangle = \frac{2}{(\alpha-1)(\alpha-2)}$$

$$\Rightarrow I_{\alpha} = \frac{\langle \Delta^2 \rangle}{\mu_{\Delta}^2} - 1 = \frac{\alpha}{\alpha-2} > 1$$

$\Rightarrow$ super-Poissonian fluctuations.

(ii) Generalized exponential: $f_{\Delta}(t) = \omega_{\beta} e^{-t^{\beta}}$, $\beta > 0$

$$\Rightarrow I_{\beta} \begin{cases} < 1 & \beta > 1 \text{ "squeezed"} \\ > 1 & \beta < 1 \text{ "stretched"} \end{cases} \text{ exponential}$$

In particular, for a semi-Gaussian distribution

$$f_{\Delta}(t) = \frac{2}{\sqrt{\pi}} e^{-t^2}$$

$$\text{and thus } I_{1/2} = \frac{\sqrt{\pi}}{2} - 1 \approx 0.772$$

Problems

III. Stochastic processes

1° Basic concepts

a) Definitions

A stochastic process is

- (i) a RV X with pdf $f(x)$
- (ii) a mapping $X \longrightarrow Y_x(t), t \in \mathbb{R}$

$Y_x(t)$ is called a realization of the process.

Two complementary points of view:

- for given X , $Y_x(t)$ is a function of t
- for given t , $Y_x(t)$ is a RV with pdf

$$\underline{P_1(y, t) = \langle \delta(y - Y_x(t)) \rangle_x}$$

Examples:

$$(i) X = (A, \omega, \phi) \in \mathbb{R}^3$$

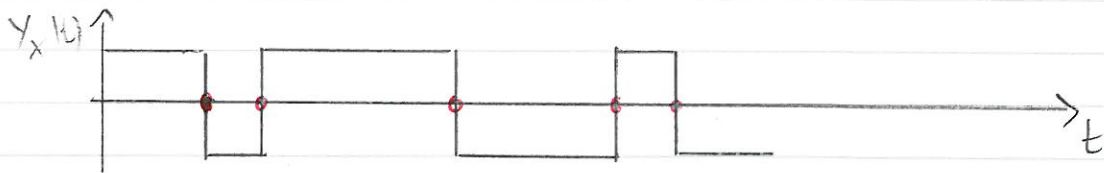
$$Y_x(t) = A \sin(\omega t + \phi)$$

↑ amplitude
 ↑ frequency
 ↑ phase

- (ii) $X = \{s; \tau_1, \dots, \tau_s\}$ a point process (Ch II)
 $Y_x(t) = N_{[0,t]}$ the corresponding counting process.
 In particular, when X is shot noise, Y_x is the Poisson process.

- (iii) Telegraph process: $X = \text{shot noise}$,

$$Y_x(t) = \begin{cases} 1 & N_{[0,t]} \text{ even} \\ -1 & N_{[0,t]} \text{ odd} \end{cases}$$



- (iv) Continuous time random walks: (see I.2°)

$$X = \{x_i, \tau_i\}$$

↑ increment ↑ waiting times

$$\Rightarrow Y_x(t) = \sum_{i=1}^{N_{[0,t]}} x_i$$

$$N_{[0,t]} = \max \left\{ n : \sum_{i=1}^n \tau_i < t \right\}$$

b) Moments and correlations

In analogy to simple RV's (Ch I) we define

omit subscript x

$$\begin{cases} \langle Y(t) \rangle := \langle Y_x(t) \rangle_x = \int dx f(x) Y_x(t) \\ \langle Y(t_1) Y(t_2) \dots Y(t_n) \rangle := \int dx f(x) Y_x(t_1) \dots Y_x(t_n) \end{cases}$$

Autocorrelation function:

$$\begin{aligned} K(t_1, t_2) &= \text{Cov}(Y(t_1), Y(t_2)) = \\ &= \langle Y(t_1) Y(t_2) \rangle - \langle Y(t_1) \rangle \langle Y(t_2) \rangle \end{aligned}$$

and in the n -dimensional case:

$$\vec{Y}(t) = (Y_1(t), \dots, Y_n(t)) \in \mathbb{R}^n$$

$$\Rightarrow \text{define } K_{ij}(t_1, t_2) = \text{Cov}(Y_i(t_1), Y_j(t_2))$$

$$\left. \begin{array}{l} i=j: \text{ autocorrelation function} \\ i \neq j: \text{ cross-correlation} \end{array} \right\}$$

In analogy to the generating function $G_x(k)$

We define the generating functional acting

on test functions $k(t)$:

$$G[k(t)] = \left\langle \exp\left(i \int_{-\infty}^{\infty} dt k(t) Y(t)\right) \right\rangle$$

with the expansion

$$G[k(t)] = \sum_{n=0}^{\infty} \frac{i^n}{n!} \int_{-\infty}^{\infty} dt_1 \dots \int_{-\infty}^{\infty} dt_n k(t_1) \dots k(t_n) \times \\ \times \langle Y(t_1) \dots Y(t_n) \rangle$$

$$\ln G[k(t)] = \sum_{n=1}^{\infty} \frac{i^n}{n!} \int_{-\infty}^{\infty} dt_1 \dots \int_{-\infty}^{\infty} dt_n k(t_1) \dots k(t_n) \times \\ \times \underbrace{\langle Y(t_1) \dots Y(t_n) \rangle_c}_{\text{cumulants}}$$

in particular, $k(t_1, t_2) = \langle Y(t_1) Y(t_2) \rangle_c$.

c) Stationarity (see II. 1°)

A stochastic process is called stationary if

$$\langle Y(t_1 + \tau) \dots Y(t_n + \tau) \rangle = \langle Y(t_1) \dots Y(t_n) \rangle$$

for all $\tau, n, t_1, \dots, t_n$. This implies

in particular that

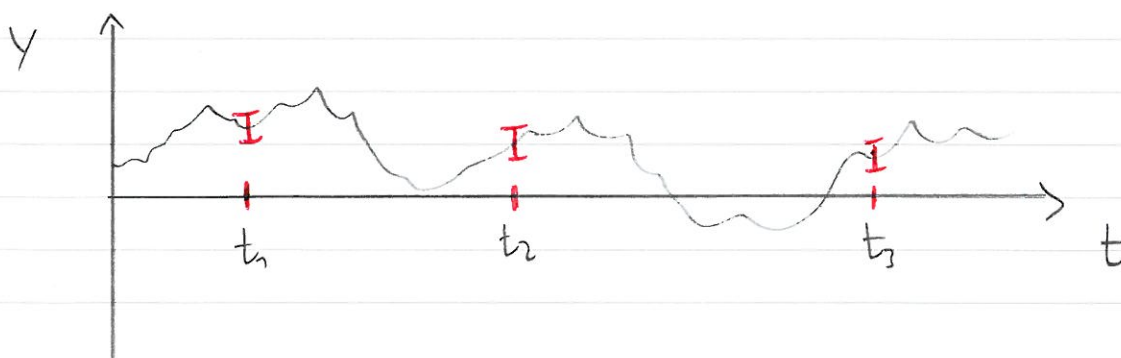
$$\left. \begin{aligned} \langle Y(t+\tau) \rangle &= \langle Y(t) \rangle = \bar{Y} = \text{const.} \\ K(t_1, t_2) &= K(t_1 - t_2) = K(t_2 - t_1) \end{aligned} \right\}$$

d) Distribution Functions

A general stochastic process can be fully characterized through the hierarchy of distribution functions defined by:

$$\begin{aligned} P_n(y_1, t_1; y_2, t_2; \dots; y_n, t_n) &= \\ &= \left\langle \prod_{i=1}^n \delta(y_i - Y_X(t_i)) \right\rangle_X \end{aligned}$$

$P_n dy_1 \dots dy_n$ is the joint probability for the process to be in $(y_1, y_1 + dy_1)$ at t_1 , $(y_2, y_2 + dy_2)$ at t_2 etc.:



Similarly conditional probabilities can be defined:

$$P_{1|1} (y_2, t_2 | y_1, t_1) = \frac{P_2(y_1, t_1; y_2, t_2)}{P_1(y_1, t_1)}$$

and generally

$$P_{k|k} (y_{k+1}, t_{k+1}; \dots; y_{k+l}, t_{k+l} | y_1, t_1; \dots; y_k, t_k) =$$

$$= \frac{P_{k+l} (y_1, t_1; \dots; y_{k+l}, t_{k+l})}{P_k (y_1, t_1; \dots; y_k, t_k)}$$

e) Gaussian processes

A stochastic process is called Gaussian, if all distribution functions $P_n (y_1, t_1; \dots; y_n, t_n)$ are $2n$ -dimensional Gaussian probability density functions (cf. I. 1° f). Then all cumulants of order ≥ 3 vanish and the generating functional (and hence the full process)

is specified by $\langle y(t) \rangle$ and $\kappa(t_1, t_2) =$

$$G[k(t)] = \exp \left[i \int_{-\infty}^{\infty} k(t_1) \langle y(t_1) \rangle dt_1 - \frac{1}{2} \int_{-\infty}^{\infty} dt_1 \int_{-\infty}^{\infty} dt_2 k(t_1) k(t_2) \kappa(t_1, t_2) \right]$$

If the process is also stationary, it is fully specified (up to a constant) by the autocorrelation function $\kappa(\tau)$.
