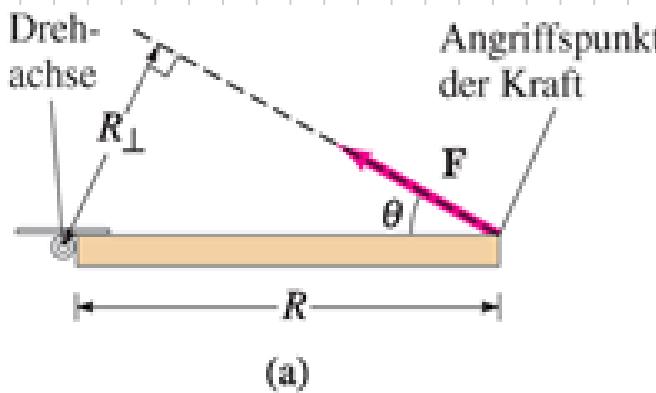


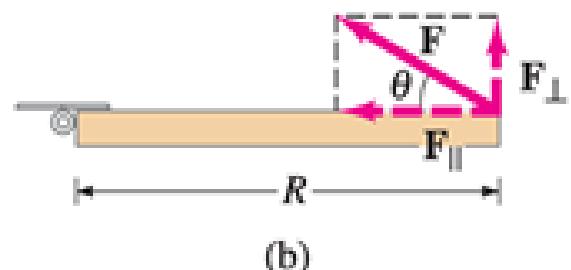
6) Vektorprodukt "äußeres Produkt": $\vec{a} \times \vec{b} = \vec{c}$

Notiztitel

05.09.2012



(a)



(b)

Drehmoment: $\vec{M} = \vec{R} \times \vec{F}$

$$|\vec{M}| = |\vec{R}_\perp| \cdot |\vec{F}| = R_\perp \cdot F$$

$$= |\vec{R}| \cdot |\vec{F}_\perp| = R \cdot F_\perp$$

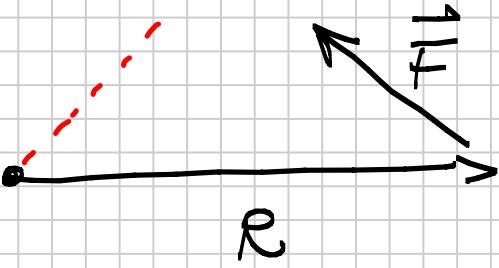
$$= R \cdot F \cdot \sin \theta$$

$$\vec{M} = \vec{R} \times \vec{F}$$

\vec{R} und \vec{F}

definieren
eine Ebene α

$$\vec{M} := \vec{R} \times \vec{F}$$



Drehachse :

ausgewichene Richtung

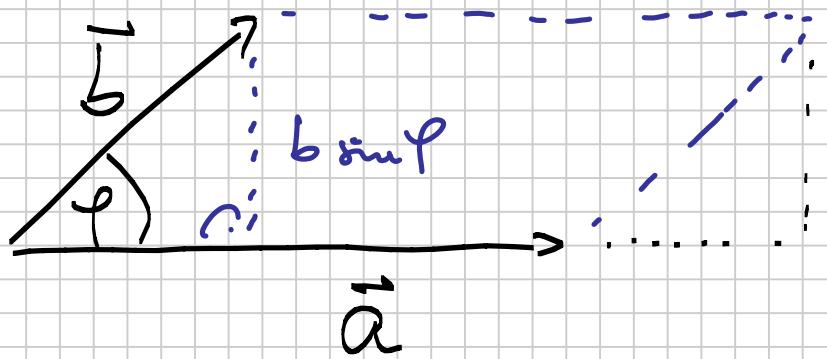
senkrecht zu \vec{R} und \vec{F}

\perp zu \vec{R}, \vec{F} - Ebene

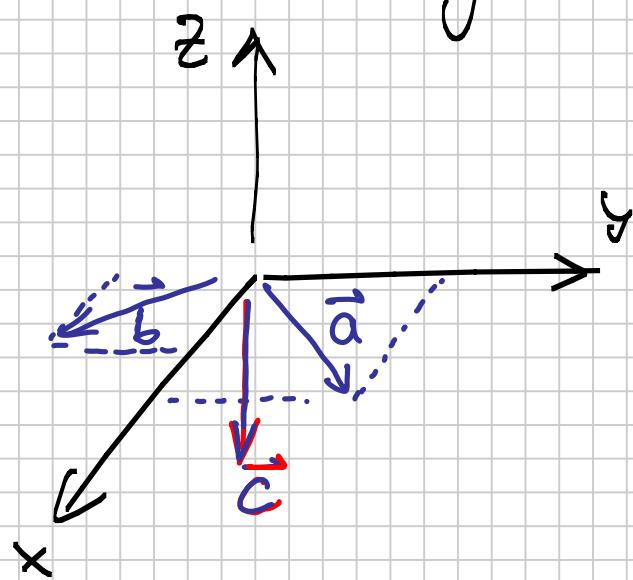
$$\vec{a} \times \vec{b} = \vec{c} \quad \text{mit} \quad 1) \quad c = ab \sin \varphi \quad \varphi = \angle(\vec{a}, \vec{b})$$

$$2) \quad \vec{c} \perp \vec{a} \quad \text{und} \quad \vec{c} \perp \vec{b}$$

3) $\vec{a}, \vec{b}, \vec{c}$ bilden ein rechts liegendes System



$$\vec{a} \times \vec{b} = \vec{c} \quad |\vec{c}| : \text{Fläche des Parallelogramms}$$

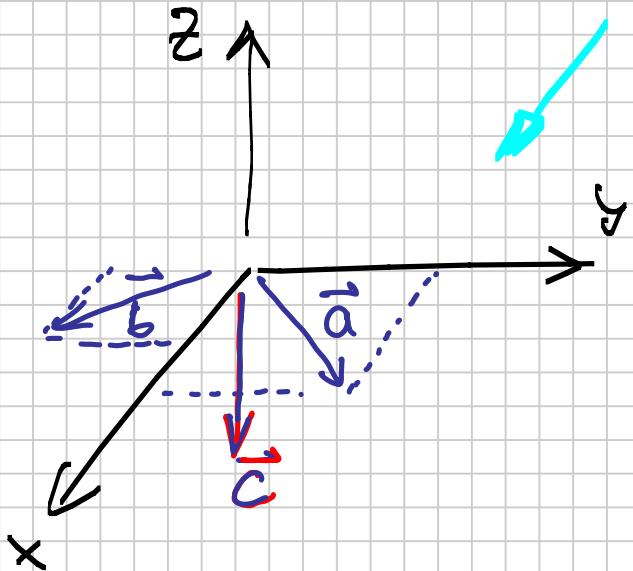


$$\vec{a} \times \vec{b} = 0 \quad (\text{falls 1) } \vec{a}=0 \text{ oder } \vec{b}=0$$

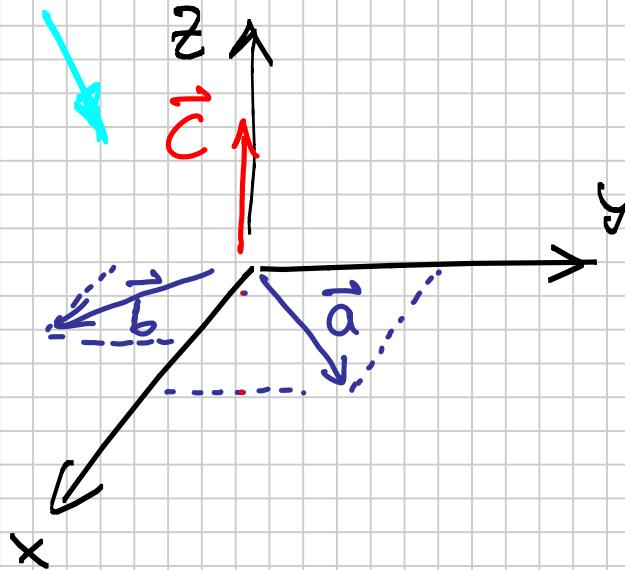
2) $\vec{b} = \alpha \vec{a}$ Parallel Vektoren

anti-kommutativ:

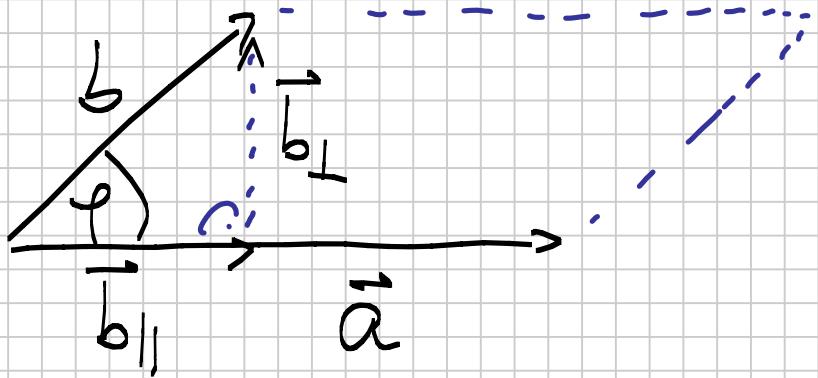
$$\vec{a} \times \vec{b} = - \vec{b} \times \vec{a}$$



Spannen eine Fläche auf



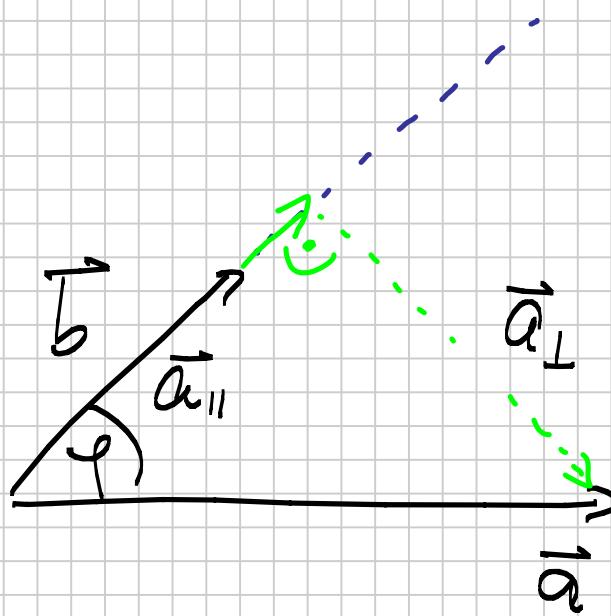
$$\vec{a} \times \vec{b} = \vec{a} \times \vec{b}_\perp = \vec{a}_\perp \times \vec{b} = \vec{c}$$



$$\vec{b} = \vec{b}_{||} + \vec{b}_\perp$$

$$|\vec{b}_\perp| = b \sin \varphi$$

$$|\vec{a} \times \vec{b}_\perp| = a b_\perp \sin 90^\circ$$



$$\vec{a} = \vec{a}_{||} + \vec{a}_\perp$$

$$|\vec{a}_\perp| = a \cdot \sin \varphi$$

$$|\vec{a}_\perp \times \vec{b}| = a_\perp b \cdot \sin 90^\circ$$

$$= ab_{\perp} = ab \sin \varphi \quad \equiv \quad a_{\perp} b = ab \sin \varphi$$

$$\vec{a} \times \vec{b} = \vec{a} \times (\vec{b}_{\perp} + \vec{b}_{\parallel}) = \vec{a} \times \vec{b}_{\perp} + \vec{a} \times \vec{b}_{\parallel} \stackrel{=} {0}$$

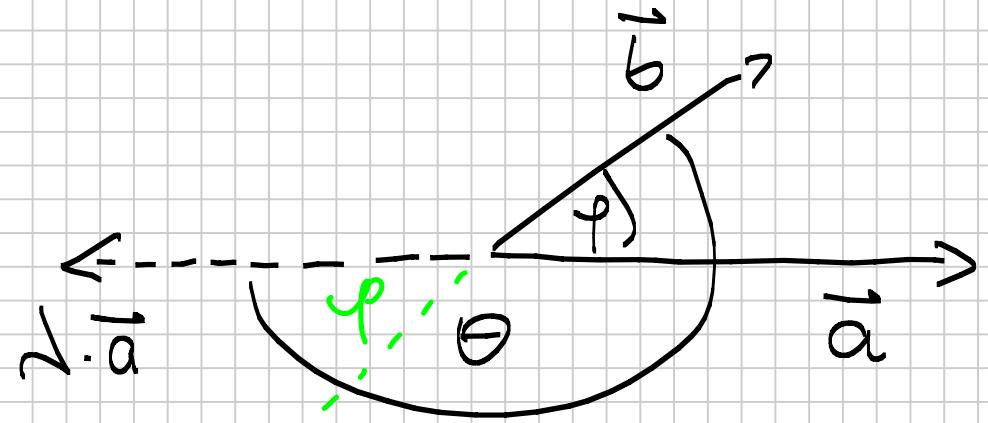
$$\vec{a} \times \vec{b} = (\vec{a}_{\perp} + \vec{a}_{\parallel}) \times \vec{b} = \vec{a}_{\perp} \times \vec{b} + \vec{a}_{\parallel} \times \vec{b} \stackrel{=} {0}$$

Bilinearität $\lambda \in \mathbb{R}$ $(\lambda \vec{a}) \times \vec{b} = \vec{a} \times (\lambda \vec{b}) = \lambda (\vec{a} \times \vec{b})$

Beweis : $\lambda \geq 0$:

$$\begin{aligned} \lambda \vec{a} \times \vec{b} &= (\lambda a) b \sin \varphi = a (\lambda b) \sin \varphi \\ &= \lambda (ab \sin \varphi) \end{aligned}$$

$$\lambda < 0 : \quad \lambda(\vec{a} \times \vec{b}) = \lambda \vec{c} = -|\lambda| \vec{c} \quad \text{mit } |\vec{c}| = ab \sin \varphi$$



$$(\lambda \cdot \vec{a}) \times \vec{b} = (-|\lambda| \vec{a}) \times \vec{b} = -|\lambda| \vec{c}$$

$$\text{denn } |\lambda| a b \sin \Theta = -|\lambda| a b \sin \varphi$$

$$\varphi + \pi = \Theta \quad \sin(\pi + \varphi) = \sin \Theta = -\sin \varphi$$

$$\vec{a} \times (\lambda \vec{b}) = \vec{a} \times (-|\lambda| \vec{b}) = -|\lambda| \vec{c}$$

$$\text{denn } a |\lambda| b \sin \Theta = -|\lambda| a b \sin \varphi$$

Distributivgesetz: $\vec{a} \times (\vec{b} + \vec{c}) = \vec{a} \times \vec{b} + \vec{a} \times \vec{c}$

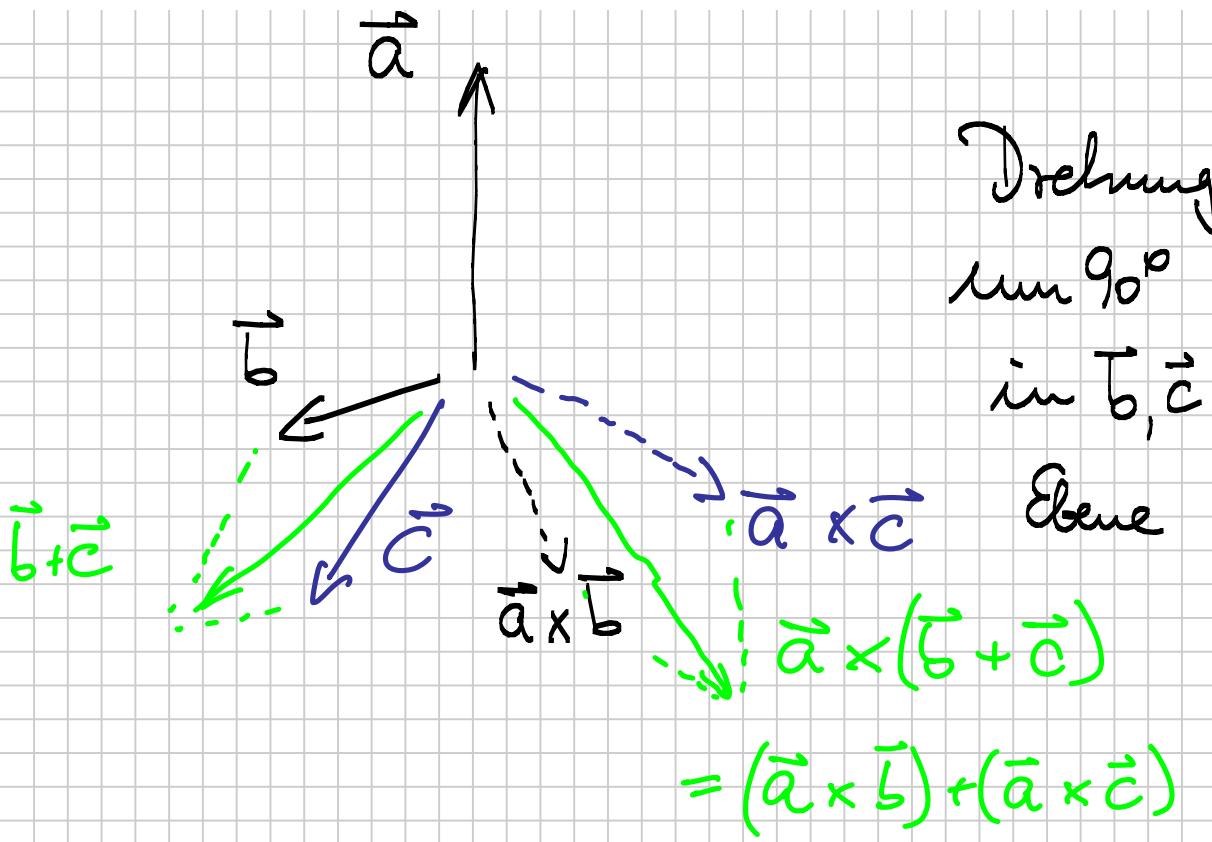
$$\vec{a} \times \vec{b} = \vec{a} \times \vec{b}_\perp ; \quad \vec{a} \times \vec{c} = \vec{a} \times \vec{c}_\perp$$

$$\vec{a} \times (\vec{b} + \vec{c}) = \vec{a} \times (\vec{b} + \vec{c})_\perp \quad \text{denn } \vec{b} + \vec{c} = (\vec{b} + \vec{c})_{||} + (\vec{b} + \vec{c})_\perp$$

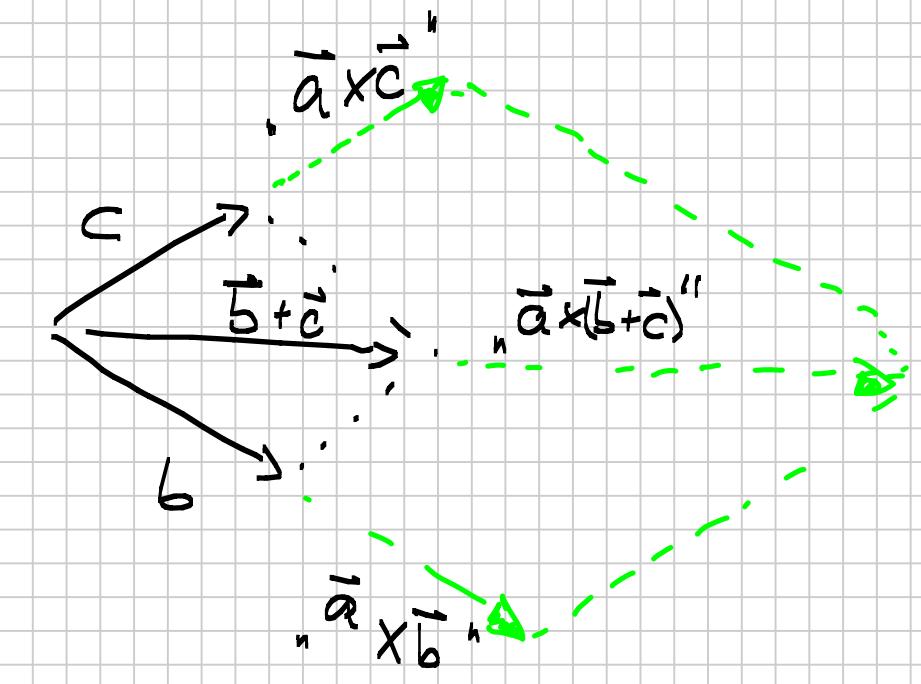
ist möglich

$$\Rightarrow \vec{a} \times (\vec{b} + \vec{c})_\perp = \vec{a} \times \vec{b}_\perp + \vec{a} \times \vec{c}_\perp ?$$

O.B.d.A. $\vec{b} \perp \vec{a}$ und $\vec{c} \perp \vec{a}$ sowie $(\vec{b} + \vec{c}) \perp \vec{a}$



\Rightarrow

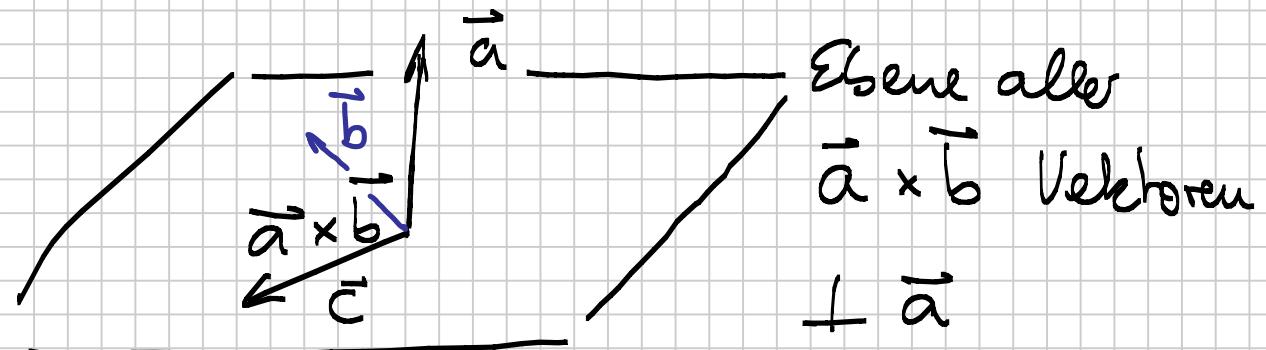


gleiche Drehung aller Vektoren mit \vec{a} !

$$\Rightarrow \vec{a} \times (\vec{b} + \vec{c}) = \vec{a} \times \vec{b} + \vec{a} \times \vec{c} \quad \text{distributiv}$$

Für \vec{a} gilt $\vec{a} \times \vec{a} = 0$ da $\sin(0^\circ) = 0$

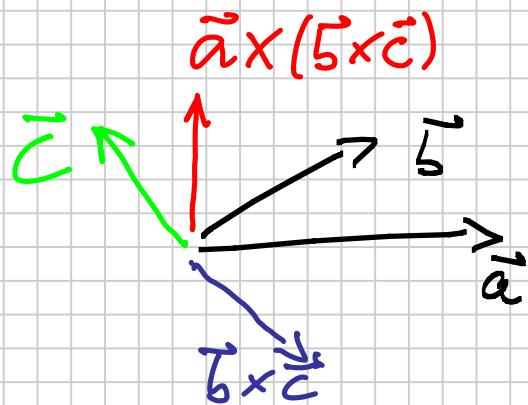
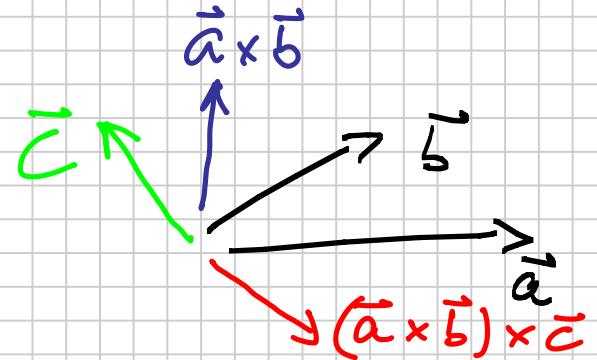
$$\vec{a} \cdot (\vec{a} \times \vec{b}) = \vec{b} \cdot (\vec{a} \times \vec{b}) = 0 \quad \text{dann } \vec{a} \times \vec{b} = \vec{c} \perp \vec{a}, \vec{b}$$



$$\begin{aligned}\vec{a} \cdot \vec{c} &= ac \cos 90^\circ = 0 \\ \vec{b} \cdot \vec{c} &= bc \cos 90^\circ = 0\end{aligned}$$

$$\text{da } \cos 90^\circ = 0$$

Vektorprodukt ist nicht assoziativ: $(\vec{a} \times \vec{b}) \times \vec{c} \neq \vec{a} \times (\vec{b} \times \vec{c})$



$\vec{a} \times \vec{b} \perp \vec{a}, \vec{b}$ Ebene $\Rightarrow (\vec{a} \times \vec{b}) \times \vec{c}$ liegt in \vec{a}, \vec{b} Ebene

$\vec{b} \times \vec{c} \perp \vec{b}, \vec{c}$ Ebene $\Rightarrow \vec{a} \times (\vec{b} \times \vec{c})$ liegt in \vec{b}, \vec{c} Ebene

Ausnahme: $\vec{a} = 0$, etc. oder $\vec{a} \times (\vec{b} \times \vec{c}) = 0 \Leftrightarrow \vec{c}$ liegt
and in \vec{a}, \vec{b} Ebene

7. Reduzieren mit Vektorprodukt in kartesischen Koordinaten

$$\vec{e}_x \times \vec{e}_y = \vec{e}_z \quad ; \quad \vec{e}_y \times \vec{e}_x = -\vec{e}_z \quad \text{denn } \vec{e}_j \perp \vec{e}_i \text{ für } i \neq j$$

$\vec{e}_x, \vec{e}_y, \vec{e}_z$ rechtsständig und $|\vec{e}_i| = 1$

allgemein:

$$\vec{e}_i \times \vec{e}_j = \begin{cases} \vec{e}_k & \text{für } i, j, k \text{ zyklisch} \\ -\vec{e}_k & \text{für } i, j, k \text{ antizyklisch} \end{cases}$$

zyklisch $\overbrace{1-2-3}, \overbrace{2-3-1}, \overbrace{3-1-2}$

$\overbrace{x-y-z}, \overbrace{y-z-x}, \dots$

anti zyklisch $1-3-2 ; 3-2-1 ; 2-1-3$

Definition: Levi-Civita Tensor ϵ_{ijk}

$$\epsilon_{ijk} = \vec{e}_i \cdot (\vec{e}_j \times \vec{e}_k) = \begin{cases} 1 & \text{für } i, j, k \text{ zyklisch} \\ -1 & \text{für } i, j, k \text{ anti zykl.} \\ 0 & \text{sonst} \end{cases}$$

total antisymmetrischer Tensor 3. Stufe

$$\vec{e}_i \times \vec{e}_j = \sum_{k=1}^3 \epsilon_{ijk} \vec{e}_k = \epsilon_{ijk} \vec{e}_k$$

$$\vec{a} \times \vec{b} = (a_1 \vec{e}_1 + a_2 \vec{e}_2 + a_3 \vec{e}_3) \times (b_1 \vec{e}_1 + b_2 \vec{e}_2 + b_3 \vec{e}_3)$$

$$= a_1 b_1 (\underbrace{\vec{e}_1 \times \vec{e}_1}_0) + a_1 b_2 (\underbrace{\vec{e}_1 \times \vec{e}_2}_{\vec{e}_3}) + a_1 b_3 (\underbrace{\vec{e}_1 \times \vec{e}_3}_{-\vec{e}_2})$$

$$+ a_2 b_1 (\underbrace{\vec{e}_2 \times \vec{e}_1}_{-\vec{e}_3}) + a_2 b_2 (\underbrace{\vec{e}_2 \times \vec{e}_2}_0) + a_2 b_3 (\underbrace{\vec{e}_2 \times \vec{e}_3}_{+\vec{e}_1})$$

$$+ a_3 b_1 (\underbrace{\vec{e}_3 \times \vec{e}_1}_{\vec{e}_2}) + a_3 b_2 (\underbrace{\vec{e}_3 \times \vec{e}_2}_{-\vec{e}_1}) + a_3 b_3 (\underbrace{\vec{e}_3 \times \vec{e}_3}_0)$$

$$= (a_2 b_3 - a_3 b_2) \vec{e}_1 + (a_3 b_1 - a_1 b_3) \vec{e}_2 + (a_1 b_2 - a_2 b_1) \vec{e}_3$$

$$\begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} \times \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix} = \begin{pmatrix} a_2 b_3 - a_3 b_2 \\ a_3 b_1 - a_1 b_3 \\ a_1 b_2 - a_2 b_1 \end{pmatrix}$$

zyklisch

-antizyklisch

Konstruktion:

$$\left| \begin{array}{ccc} e_1 & e_2 & e_3 \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{array} \right| \left| \begin{array}{cc} e_1 & e_2 \\ a_1 & a_2 \\ b_1 & b_2 \end{array} \right| = \vec{e}_1 (a_2 b_3 - a_3 b_2) + \vec{e}_2 (a_3 b_1 - a_1 b_3) + \vec{e}_3 (a_1 b_2 - a_2 b_1)$$

$$\vec{C} = (\vec{a} \times \vec{b}) = a_i \vec{e}_i \times b_j \vec{e}_j = a_i b_j \vec{e}_i \times \vec{e}_j$$

$$= a_i b_j \epsilon_{ijk} \vec{e}_k = c_k \vec{e}_k$$

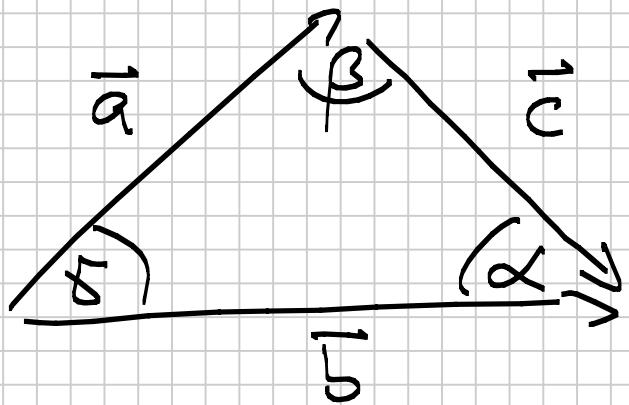
mit $c_k = \epsilon_{ijk} a_i b_j = \sum_{i,j=1}^3 a_i b_j \epsilon_{ijk}$

$$c_1 = a_2 b_3 - a_3 b_2$$

$$c_2 = a_3 b_1 - a_1 b_3$$

$$c_3 = a_1 b_2 - a_2 b_1$$

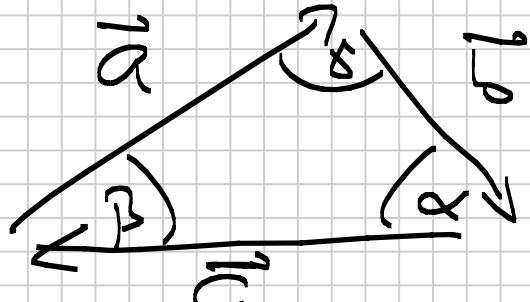
7.1. Cosinusatz und Sinusatz:



$$\vec{c} = -\vec{a} + \vec{b} = \vec{b} - \vec{a}$$

$$\vec{c}^2 = c^2 = (\vec{b} - \vec{a})^2 = b^2 + a^2 - 2\vec{a}\vec{b}$$

$$\underline{c^2 = a^2 + b^2 + 2ab \cos \gamma}$$



$$\vec{a} + \vec{b} + \vec{c} = 0$$

$$\vec{a} \times \vec{b} = \vec{a} \times (0 - \vec{c} - \vec{a}) = \overbrace{\vec{c} \times \vec{a}}^{=0} - \vec{a} \times \vec{c} - \underbrace{\vec{a} \times \vec{a}}_{=0}$$

andergesieh $\vec{a} \times \vec{b} = (-\vec{c} - \vec{b}) \times \vec{b} = -\vec{c} \times \vec{b} = \vec{b} \times \vec{c}$

$$\Rightarrow \vec{a} \times \vec{b} = \vec{b} \times \vec{c} = \vec{c} \times \vec{a}$$

oder $ab \sin(180 - \gamma) = bc \sin(180 - \alpha) = ac \sin(180 - \beta)$

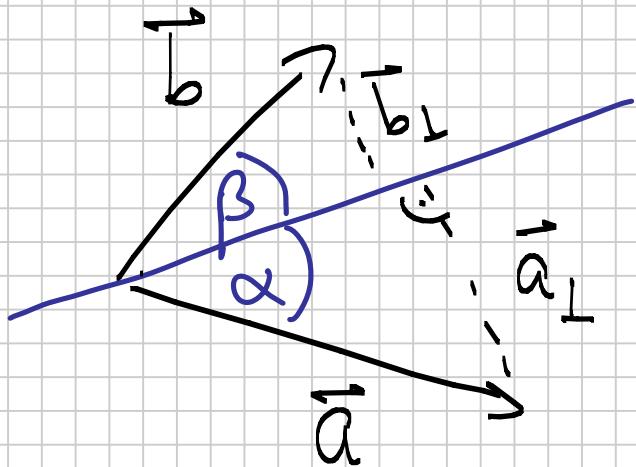
Wg $\sin(180 - \ell) = \sin \varphi$

$$ab \sin \delta = bc \sin \alpha = ac \sin \beta \quad | : abc$$

$$\frac{\sin \delta}{c} = \frac{\sin \alpha}{a} = \frac{\sin \beta}{b} \quad \text{oder}$$

$$\frac{c}{\sin \delta} = \frac{b}{\sin \beta} = \frac{a}{\sin \alpha}$$

7.2 Additionstheoreme:



$$\begin{aligned}
 \vec{a} \cdot \vec{b} &= ab \cos(\alpha + \beta) = (\vec{a}_{\parallel} + \vec{a}_{\perp})(\vec{b}_{\parallel} + \vec{b}_{\perp}) \\
 &= a_{\parallel} b_{\parallel} - a_{\perp} b_{\perp} \\
 &= a \cos \alpha b \cos \beta - a \sin \alpha b \sin \beta
 \end{aligned}$$

$$\cos(\alpha + \beta) = \cos \alpha \cos \beta - \sin \alpha \sin \beta$$

$$\begin{aligned}
 |\vec{a} \times \vec{b}| &= ab \sin(\alpha + \beta) = (\vec{a}_{\parallel} + \vec{a}_{\perp}) \times (\vec{b}_{\parallel} + \vec{b}_{\perp}) \\
 &= a_{\parallel} b_{\perp} + a_{\perp} b_{\parallel} = ab \cos \alpha \sin \beta + ab \sin \alpha \cos \beta
 \end{aligned}$$

$$\sin(\alpha + \beta) = \underline{\cos \alpha \sin \beta + \sin \alpha \cos \beta}$$

7.3. Entwicklungssatz: „bac - cab“ Regel

$$\vec{p} = \underline{\vec{a} \times (\vec{b} \times \vec{c})} = \vec{b}(\vec{a} \cdot \vec{c}) - \vec{c}(\vec{a} \cdot \vec{b}) = \underbrace{\beta \vec{b} + \gamma \vec{c}}_{\vec{p}} = \vec{p}$$

$$\vec{p} \perp \vec{a} \Rightarrow \vec{p} \cdot \vec{a} = 0 = \beta \vec{b} \cdot \vec{a} + \gamma \vec{c} \cdot \vec{a} \quad \vec{p} \text{ liegt in } \vec{b}, \vec{c} \text{ Ebene}$$

$$\text{Sei } \alpha := \frac{\beta}{\vec{a} \cdot \vec{c}} \Rightarrow \alpha = -\frac{\beta}{\vec{c} \cdot \vec{a}} \vec{b} \cdot \vec{a} = -\alpha \vec{b} \cdot \vec{a}$$

$$\Rightarrow \vec{p} = \beta \vec{b} + \gamma \vec{c} = \alpha [\vec{b}(\vec{a} \cdot \vec{c}) - \vec{c}(\vec{a} \cdot \vec{b})] = \vec{a} \times (\vec{b} \times \vec{c})$$

Sei $\vec{a}, \vec{b}, \vec{c} \neq 0$ und $\vec{a} \times (\vec{b} \times \vec{c}) \neq 0$

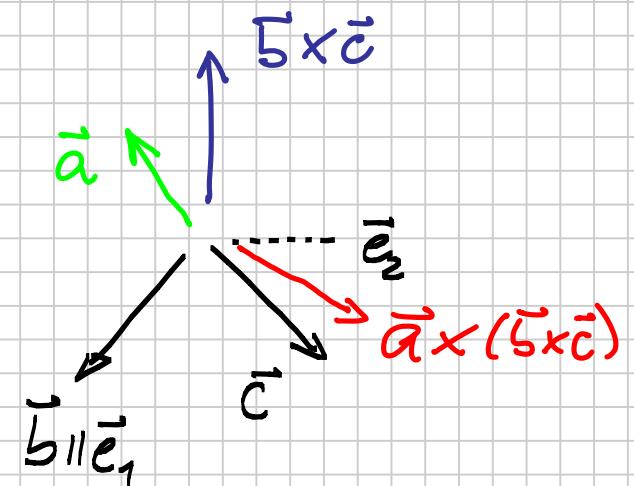
Wähle $\vec{e}_1 \parallel \vec{b}$ und \vec{e}_2 in b, c -Ebene

also $\vec{b} = b \vec{e}_1$ und $\vec{c} = c_1 \vec{e}_1 + c_2 \vec{e}_2$

$$\Rightarrow \vec{b} \times \vec{c} = b c_2 \cdot \vec{e}_3$$

$$\Rightarrow \vec{a} \times (\vec{b} \times \vec{c}) = b c_2 (\vec{a} \times \vec{e}_3) = b c_2 (a_1 \vec{e}_1 \times \vec{e}_3 + a_2 \vec{e}_2 \times \vec{e}_3 + a_3 \vec{e}_3 \times \vec{e}_3)$$

$$= \begin{pmatrix} b c_2 a_2 \\ -b c_2 a_1 \\ 0 \end{pmatrix}$$



Anderson's:

$$\alpha [\vec{b}(\vec{a}\vec{c}) - \vec{c}(\vec{a}\vec{b})] = \alpha [b\vec{e}_1(a_1c_1 + a_2c_2) - (c_1\vec{e}_1 + c_2\vec{e}_2)(a_1b)]$$

$$= \alpha [\vec{e}_1(ba_1c_1 + a_2c_2b - a_1c_1b) - a_1c_2b\vec{e}_2]$$

$$= \alpha \begin{pmatrix} a_2c_2b \\ a_1c_2b \\ 0 \end{pmatrix} \quad \xrightarrow{\quad} \quad \alpha = 1$$

\Rightarrow Entwicklungsgesetz gilt:

$$\underline{\vec{a} \times (\vec{b} \times \vec{c}) = \vec{b}(\vec{a} \cdot \vec{c}) - \vec{c}(\vec{a} \cdot \vec{b})}$$