

# LANGEVIN EQUATION AND THERMODYNAMICS

## RELATING STOCHASTIC DYNAMICS WITH THERMODYNAMIC LAWS

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November 10, 2017



# MOTIVATION

- There are at least three levels of description of classical dynamics: **thermodynamic**, **stochastic** and **microscopic**
- Thermodynamics and microscopic Hamiltonian dynamics are connected by Boltzmann formalism. Similarly, how do we relate thermodynamics to stochastic dynamics?
- More specifically, can the laws of thermodynamics be applied to stochastic, non equilibrium systems?



# LANGEVIN EQUATION

- We begin from Langevin and Fokker-Planck equation
- Langevin equation:

$$\dot{x} = \mu F(x, \lambda) + \zeta \quad (1)$$

where the force  $F(x, \lambda) = -\partial_x V(x, \lambda) + f(x, \lambda)$

- $\lambda$  is an external control parameter of the force
- The noise characterized by  $\langle \zeta(\tau) \rangle = 0$  and  $\langle \zeta(\tau) \zeta(\tau') \rangle = 2D\delta(\tau - \tau')$  with  $D = \mu T$  (Einstein relation)



# FOKKER-PLANCK EQUATION

- Fokker Planck equation:

$$\begin{aligned}\partial_{\tau}p(x, \tau) &= -\partial_x j(x, \tau) \\ &= -\partial_x(\mu F(x, \lambda)p(x, \tau) - D\partial_x p(x, \tau))\end{aligned}\quad (2)$$

- The Langevin equation describes the evolution of an individual trajectory, while the Fokker-Planck describes the evolution of the ensemble.



# LANGEVIN AND FOKKER-PLANCK EQUATION

- Path integral representation to Langevin dynamics:

$$\begin{aligned} p[x(\tau)|x_0] &\equiv \exp\left[-\int_0^t d\tau \left(\frac{(\dot{x} - \mu F)^2}{4D} + \frac{\mu \partial_x F}{2}\right)\right] \\ &\equiv \exp[-\mathcal{A}[x(\tau)]] \end{aligned} \quad (3)$$

- Here the action  $\mathcal{A} = \frac{1}{D} \int L d\tau$  with the Lagrangian

$$L = \frac{(\dot{x} - \mu F)^2}{4} + \frac{\mu D \partial_x F}{2}$$



# LANGEVIN DYNAMICS

## PATH INTEGRAL FORMALISM

- We have the Langevin equation  $\dot{x} = \mu F(x, \lambda) + \zeta$
- We discretize time ( $t \equiv i\epsilon$ ,  $i = 0, \dots, N$ ) and rewrite discrete Langevin equation (Stratonovich discretization).

$$\frac{x_i - x_{i-1}}{\epsilon} = \frac{\mu}{2}[F_i(x_i) + F_{i-1}(x_{i-1})] + \zeta_i \quad (4)$$

- The probability distribution of the  $x_i$  is related to the Gaussian noise distribution with a transformation Jacobian.

$$p(\{x_i\}|x_0) = \det\left(\frac{\partial \zeta_j}{\partial x_i}\right) p(\{\zeta_j\}) \quad (5)$$



# LANGEVIN DYNAMICS

## PATH INTEGRAL FORMALISM

- The noise distribution is Gaussian  $p(\zeta_j) \sim \exp(-\frac{\epsilon}{4D}\zeta_j^2)$  and the first two moments are characterized by  $\langle \zeta_j \rangle = 0$  and  $\langle \zeta_i \zeta_j \rangle = \frac{2D}{\epsilon} \delta_{ij}$
- The Gaussian noise translates into the Gaussian part of the action, the determinant yields the non-Gaussian force derivative contribution.
- In discrete form the equation becomes:

$$p(\{x_i\}|x_0) \equiv \exp\left[-\frac{1}{4D\epsilon} \left[ \sum_{i=1}^N (x_i - x_{i-1} - \epsilon\mu F_i(x_i))^2 - \frac{\epsilon\mu}{2} \sum_{i=1}^N \partial_{x_i} F_i(x_i) \right]\right] \quad (6)$$

- $\epsilon \rightarrow 0$  yields the continuous limit.



# FIRST LAW

- Here we identify heat dissipated by the system as  $q$  (contrary to our usual thermodynamic convention). So  $dq = -dQ$
- Potential has two contributions:  $dV = \frac{\partial V}{\partial \lambda} d\lambda + \frac{\partial V}{\partial x} dx$
- external work done:  $dw = \frac{\partial V}{\partial \lambda} d\lambda + f dx$
- From energy conservation then, heat dissipated is

$$\begin{aligned} dq &= dw - dV \\ &= F dx \end{aligned} \tag{7}$$

- For an individual trajectory then,  
 $w[x(\tau)] - q[x(\tau)] = \int_0^t d\tau \left[ \frac{\partial V}{\partial \lambda} \dot{\lambda} + \frac{\partial V}{\partial x} \dot{x} \right] = V(x_t, \lambda_t) - V(x_0, \lambda_0)$





# SECOND LAW

## STOCHASTIC ENTROPY

- Total entropy of the given system:

$$S(\tau) = - \int dx p(x, \tau) \ln p(x, \tau) \quad (8)$$

- This can be rewritten as  $S(\tau) = \langle -\ln p(x, \tau) \rangle_{neq}$
- We identify the **stochastic entropy** as  $s(\tau) = -\ln p(x, \tau)$  so that system entropy  $S(\tau) = \langle s(\tau) \rangle_{neq}$ .
- Stochastic entropy change is then  $\Delta s = -\ln \frac{p(x_t, \lambda_t)}{p(x_0, \lambda_0)}$



# SECOND LAW

## INTEGRAL FLUCTUATION THEOREM

- Total entropy change along a trajectory  $\Delta S_{tot} \equiv \Delta S_m + \Delta s$
- Our claim is that using  $p[x(\tau)|x_0] \equiv \exp[-\mathcal{A}[x(\tau)]]$  and the concept of time reversed paths, we will present a stronger form of the second law of Thermodynamics.
- This is the Integral Fluctuation Theorem (IFT) that states that  $\Delta S_{tot}$  follows the equality  $\langle \exp(-\Delta S_{tot}) \rangle = 1$



# SECOND LAW

## TIME FORWARD AND TIME REVERSED

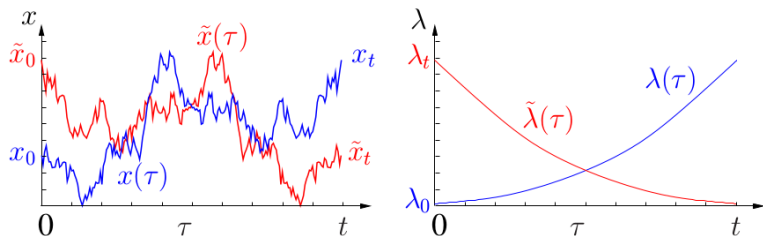


Figure: Time forward (blue) and time reversed (red) trajectories of position and external parameter  $\lambda$  [4]. Mathematically,  $\tilde{\lambda}(\tau) \equiv \lambda(t - \tau)$ ,  $\tilde{x}(\tau) \equiv x(t - \tau)$ . So,  $\tilde{x}_t = x_0$  and  $\tilde{x}_0 = x_t$ .

## SECOND LAW

### PROOF OF IFT

- We begin with  $p[x(\tau)|x_0] \equiv \exp[-\mathcal{A}[x(\tau)]]$
- For time reversed path:  $p[\tilde{x}(\tau)|\tilde{x}_0] \equiv \exp[-\tilde{\mathcal{A}}[\tilde{x}(\tau)]]$
- Since  $A[x(\tau)] = \int_0^t d\tau \left( \frac{(\dot{x} - \mu F)^2}{4D} + \frac{\mu \partial_x F}{2} \right)$ ,  $\tilde{A}[\tilde{x}(\tau)]$  is given by  $\int_0^t d\tau \left( \frac{(\dot{\tilde{x}} - \mu F)^2}{4D} + \frac{\mu \partial_{\tilde{x}} F}{2} \right)$
- Because only  $\dot{x}$  is odd under time reversal, in the ratio of probabilities only the cross term remains

$$\begin{aligned} \frac{p[x(\tau)|x_0]}{p[\tilde{x}(\tau)|\tilde{x}_0]} &= \exp \left[ \frac{\mu}{D} \int_0^t d\tau \dot{x}(\tau) F(x(\tau), \lambda(\tau)) \right] \\ &= \exp[q[x(\tau)]/T] \\ &= \exp[\Delta S_m] \end{aligned} \tag{9}$$



# PROOF OF IFT

## NORMALIZATION

- If we sum over all possible paths originating in  $x_0$ , then it will sum up to one.  $1 = \int_{x_0} d[x(\tau)]\rho[x(\tau)|x_0]$

$$\begin{aligned} 1 &= \int \rho_0(x_0) dx_0 \int_{x_0} d[x(\tau)]\rho[x(\tau)|x_0] \\ &= \int d[x(\tau)]\rho[x(\tau)|x_0]\rho_0(x_0) \end{aligned} \quad (10)$$

- Similarly for the time reversed path:

$$1 = \int d[\tilde{x}(\tau)]\rho[\tilde{x}(\tau)|\tilde{x}_0]\rho_1(\tilde{x}_0) \quad (11)$$



# PROOF OF IFT

- We rewrite eq. 11 as:

$$1 = \int d[\tilde{x}(\tau)] p[x(\tau)|x_0] p_0(x_0) \frac{p[\tilde{x}(\tau)|\tilde{x}_0] p_1(\tilde{x}_0)}{p[x(\tau)|x_0] p_0(x_0)} \quad (12)$$

- Sum over backward paths is equivalent to sum over forward paths.

$$1 = \int d[x(\tau)] p[x(\tau)|x_0] p_0(x_0) \exp[-\Delta S_m] \frac{p_1(x_t)}{p_0(x_0)} \quad (13)$$

- So  $\langle \exp[-\Delta S_m] \frac{p_1(x_t)}{p_0(x_0)} \rangle = 1$



## SECOND LAW

### PROOF OF IFT

- By definition of Stochastic entropy,  $\Delta s = -\ln \frac{\rho(x_t, \lambda_t)}{\rho(x_0, \lambda_0)}$
- $\rho_1(x_t)$  was the initial distribution of the time reversed path, or in other words the final distribution of the time forward path.
- So we gain  $\langle \exp(-\Delta S_m - \Delta s) \rangle = \langle \exp(-\Delta S_{tot}) \rangle = 1$
- This is the formulation of Integral Fluctuation Theorem (IFT). Using Jensen's inequality ( $\langle e^x \rangle \geq e^{\langle x \rangle}$ ) one gets back  $\langle \Delta S_{tot} \rangle \geq 0$ .



# JARZYNSKI RELATION

- In our expression  $\langle \exp[-\Delta S_m] \frac{p_1(x_t)}{p_0(x_0)} \rangle = 1$ , if we consider initial and final states to be equilibrium states, then:

$$p_0(x) = \frac{1}{Z} e^{-\frac{V(x, \lambda_0)}{T}} = e^{-\frac{V(x, \lambda_0) - \mathcal{F}(\lambda_0)}{T}}$$

- Similarly  $p_1(x) = e^{-\frac{V(x, \lambda_t) - \mathcal{F}(\lambda_t)}{T}}$
- Putting in the values:

$$\left\langle \exp\left[-\frac{q}{T}\right] \exp\left[-\frac{\Delta V - \Delta \mathcal{F}}{T}\right] \right\rangle = 1$$

- Using  $q = w - \Delta V$ , we find that:

$$\langle \exp[-w/T] \rangle = \exp[-\Delta \mathcal{F}/T] \quad (14)$$

- This is the **Jarzynski relation** which relates equilibrium free energy difference with non equilibrium work.





# CONCLUSION

- Our aim was to demonstrate how one can relate laws of Thermodynamics to stochastic non equilibrium systems.
- We find that the first law can be applied on the level of individual trajectories.
- Using the concept of time forward and time reversed paths, we derived a stronger statement of the second law of thermodynamics valid for an ensemble.
- From IFT, one can derive the Jarzynski relation that relates the free energy difference of states with non equilibrium work.



# REFERENCES

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# THANK YOU



# JENSEN'S INEQUALITY

- A convex function is a continuous function whose value at the midpoint of every interval in its domain does not exceed the arithmetic mean of its values at the ends of the interval.

$$\lambda f(x_1) + (1 - \lambda)f(x_2) \geq f(\lambda x_1 + (1 - \lambda)x_2)$$

- This generalizes to:

$$\sum_{i=1}^N a_i f(x_i) \geq f\left(\sum_{i=1}^N a_i x_i\right)$$

with  $\sum_{i=1}^N a_i = 1$

- We take  $a_i = 1/N$  and identify  $f(x) = e^x$  as a convex function.
- We get  $\langle e^x \rangle \geq e^{\langle x \rangle}$

