

Blatt 8

Aufgabe 1: Skalar- und Kreuzprodukt

a) zu zeigen: $\vec{a} \times (\vec{b} \times \vec{c}) = \vec{b}(\vec{a} \cdot \vec{c}) - \vec{c}(\vec{a} \cdot \vec{b})$

$$\begin{aligned} \vec{a} \times (\vec{b} \times \vec{c}) &= \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} \times \begin{pmatrix} b_2 c_3 - b_3 c_2 \\ b_3 c_1 - b_1 c_3 \\ b_1 c_2 - b_2 c_1 \end{pmatrix} = \begin{pmatrix} a_2 b_1 c_2 - a_2 b_2 c_1 - a_3 b_3 c_1 + a_3 b_1 c_3 \\ a_3 b_2 c_3 - a_3 b_3 c_2 - a_1 b_1 c_2 + a_1 b_2 c_1 \\ a_1 b_3 c_1 - a_1 b_1 c_3 - a_2 b_2 c_3 + a_2 b_3 c_2 \end{pmatrix} = \\ &= \begin{pmatrix} b_1(a_2 c_2 + a_3 c_3) - c_1(a_2 b_2 + a_3 b_3) \\ b_2(a_1 c_1 + a_3 c_3) - c_2(a_1 b_1 + a_3 b_3) \\ b_3(a_1 c_1 + a_2 c_2) - c_3(a_1 b_1 + a_2 b_2) \end{pmatrix} + \underbrace{\begin{pmatrix} b_1 a_1 c_1 - c_1 a_1 b_1 \\ b_2 a_2 c_2 - c_2 a_2 b_2 \\ b_3 a_3 c_3 - c_3 a_3 b_3 \end{pmatrix}}_{= \vec{0}} = \\ &= \vec{b}(\vec{a} \cdot \vec{c}) - \vec{c}(\vec{a} \cdot \vec{b}) \quad \checkmark \end{aligned}$$

b) zu zeigen: $(\vec{a} \cdot \vec{b}) \cdot (\vec{a} \times \vec{b}) = (ab)^2 - (\vec{a} \cdot \vec{b})^2$

$$\begin{aligned} \text{linke Seite: } &\begin{pmatrix} a_2 b_3 - a_3 b_2 \\ a_3 b_1 - a_1 b_3 \\ a_1 b_2 - a_2 b_1 \end{pmatrix} \cdot \begin{pmatrix} a_2 b_3 - a_3 b_2 \\ a_3 b_1 - a_1 b_3 \\ a_1 b_2 - a_2 b_1 \end{pmatrix} = a_2^2 b_3^2 + a_3^2 b_2^2 - 2a_2 a_3 b_2 b_3 \\ &+ a_3^2 b_1^2 + a_1^2 b_3^2 - 2a_3 a_1 b_3 b_1 \\ &+ a_1^2 b_2^2 + a_2^2 b_1^2 - 2a_1 a_2 b_1 b_2 \end{aligned}$$

$$\text{rechte Seite: } a^2 b^2 - (a_1 b_1 + a_2 b_2 + a_3 b_3)^2 =$$

$$\begin{aligned} &= \underbrace{(a_1^2 + a_2^2 + a_3^2)(b_1^2 + b_2^2 + b_3^2)}_{\text{ausmultiplizieren ...}} - (a_1^2 b_1^2 + a_2^2 b_2^2 + a_3^2 b_3^2 + 2a_1 a_2 b_1 b_2 \\ &\quad + 2a_1 a_3 b_1 b_3 + 2a_2 a_3 b_2 b_3) \quad \checkmark \end{aligned}$$

Aufgabe 2: Drehmatrizen

$$D_\varphi = \begin{pmatrix} \cos \varphi & -\sin \varphi \\ \sin \varphi & \cos \varphi \end{pmatrix}$$

$$a) \quad \varphi_1 = 0 \rightarrow D_{\varphi_1} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \quad \varphi_2 = \frac{\pi}{4} \rightarrow D_{\varphi_2} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}$$

$$\varphi_3 = \frac{\pi}{2} \rightarrow D_{\varphi_3} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}, \quad \varphi_4 = \pi \rightarrow D_{\varphi_4} = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$b, \quad \vec{a} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \quad \vec{b} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$D_0 \vec{a} = \vec{a}, \quad D_{\pi/4} \vec{a} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \quad D_{\pi/2} \vec{a} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \quad D_{\pi} \vec{a} = \begin{pmatrix} -1 \\ 0 \end{pmatrix}$$

$$D_0 \vec{b} = \vec{b}, \quad D_{\pi/4} \vec{b} = \begin{pmatrix} 0 \\ \sqrt{2} \end{pmatrix}, \quad D_{\pi/2} \vec{b} = \begin{pmatrix} -1 \\ 1 \end{pmatrix}, \quad D_{\pi} \vec{b} = \begin{pmatrix} -1 \\ -1 \end{pmatrix}$$

$$c, \quad \text{zu zeigen: } D_{\varphi}^t = D_{\varphi}^{-1} \quad \text{d.h.} \quad D_{\varphi}^t D_{\varphi} = \mathbb{1}$$

$$\rightarrow \begin{pmatrix} \cos \varphi & \sin \varphi \\ -\sin \varphi & \cos \varphi \end{pmatrix} \begin{pmatrix} \cos \varphi & -\sin \varphi \\ \sin \varphi & \cos \varphi \end{pmatrix} = \begin{pmatrix} \cos^2 \varphi + \sin^2 \varphi & 0 \\ 0 & \cos^2 \varphi + \sin^2 \varphi \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$d, \quad D_{\varphi} D_{\bar{\varphi}} = \begin{pmatrix} \cos \varphi & -\sin \varphi \\ \sin \varphi & \cos \varphi \end{pmatrix} \begin{pmatrix} \cos \bar{\varphi} & -\sin \bar{\varphi} \\ \sin \bar{\varphi} & \cos \bar{\varphi} \end{pmatrix} = \begin{pmatrix} \cos \varphi \cos \bar{\varphi} - \sin \varphi \sin \bar{\varphi} & -\cos \varphi \sin \bar{\varphi} - \sin \varphi \cos \bar{\varphi} \\ \sin \varphi \cos \bar{\varphi} + \cos \varphi \sin \bar{\varphi} & -\sin \varphi \sin \bar{\varphi} + \cos \varphi \cos \bar{\varphi} \end{pmatrix}$$

$$= \begin{pmatrix} \cos(\varphi + \bar{\varphi}) & -\sin(\varphi + \bar{\varphi}) \\ \sin(\varphi + \bar{\varphi}) & \cos(\varphi + \bar{\varphi}) \end{pmatrix} = D_{\varphi + \bar{\varphi}}$$

$$e, \quad \vec{r}' = D_{\varphi} \vec{r} = \begin{pmatrix} \cos \varphi & -\sin \varphi \\ \sin \varphi & \cos \varphi \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} a \cos \varphi - b \sin \varphi \\ a \sin \varphi + b \cos \varphi \end{pmatrix}$$

$$\Rightarrow |\vec{r}'|^2 = a^2 \cos^2 \varphi + b^2 \sin^2 \varphi - 2ab \cos \varphi \sin \varphi$$

$$+ a^2 \sin^2 \varphi + b^2 \cos^2 \varphi + 2ab \cos \varphi \sin \varphi = (a^2 + b^2) \underbrace{(\cos^2 \varphi + \sin^2 \varphi)}_{=1} = |\vec{r}|^2$$

Aufgabe 3: Matrixmultiplikation

$$a, \quad A = \begin{pmatrix} 1 & 3 \\ -1 & 0 \\ 4 & -2 \end{pmatrix}, \quad B = \begin{pmatrix} 4 & 3 & -1 \\ -1 & 0 & 1 \end{pmatrix}, \quad C = (1 \ 3)$$

$$CBA B = (25 \ 18 \ -7), \quad CB = (1 \ 3 \ 2)$$

$$CBAB - 3CB = (22 \ 9 \ -13)$$

$$b, \quad A = \begin{pmatrix} a & b \\ -a & b \end{pmatrix}, \quad B = \begin{pmatrix} b & -b \\ -a & b \end{pmatrix}$$

$$[A, B]_- = AB - BA =$$

$$= \underbrace{\begin{pmatrix} a & b \\ -a & b \end{pmatrix} \begin{pmatrix} b & -b \\ -a & b \end{pmatrix}}_{\begin{pmatrix} 0 & b^2 - ab \\ -2ab & b^2 + ab \end{pmatrix}} - \underbrace{\begin{pmatrix} b & -b \\ -a & b \end{pmatrix} \begin{pmatrix} a & b \\ -a & b \end{pmatrix}}_{\begin{pmatrix} 2ab & 0 \\ -a^2 - ab & b^2 - ab \end{pmatrix}} = \begin{pmatrix} -2ab & b^2 - ab \\ a^2 - ab & 2ab \end{pmatrix}$$

$$c, \quad (A)_{ij} = a, \quad (B)_{ij} = b_j \delta_{im}, \quad (C)_{ij} = c_i \delta_{mj}, \quad (D)_{ij} = d_i \delta_{ij}$$

$$N = 4, \quad m = 2$$

$$\rightarrow A = \begin{pmatrix} a & a & a & a \\ a & a & a & a \\ a & a & a & a \\ a & a & a & a \end{pmatrix}, \quad B = \begin{pmatrix} 0 & 0 & 0 & 0 \\ b_1 & b_2 & b_3 & b_4 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \quad C = \begin{pmatrix} 0 & c_1 & 0 & 0 \\ 0 & c_2 & 0 & 0 \\ 0 & c_3 & 0 & 0 \\ 0 & c_4 & 0 & 0 \end{pmatrix}$$

$$D = \begin{pmatrix} d_1 & 0 & 0 & 0 \\ 0 & d_2 & 0 & 0 \\ 0 & 0 & d_3 & 0 \\ 0 & 0 & 0 & d_4 \end{pmatrix}$$

$$d, \quad N \in \mathbb{N}, \quad 1 < m < N$$

$$(A^2)_{ij} = \sum_{k=1}^N (A)_{ik} (A)_{kj} = N a^2$$

$$n \in \mathbb{N}, \quad (D^n)_{ij} = d_i^n \delta_{ij}$$

$$(BC)_{ij} = \sum_{k=1}^N (B)_{ik} (C)_{kj} = \sum_{k=1}^N b_k \delta_{im} c_k \delta_{mj} = \delta_{im} \delta_{mj} \sum_k b_k c_k$$

$$\text{d.h. } (BC)_{mm} = \sum_k b_k c_k \quad \text{und alle anderen Matrixelemente} = 0$$

$$(CB)_{ij} = \sum_{k=1}^N (C)_{ik} (B)_{kj} = \sum_{k=1}^N c_i \delta_{mk} b_j \delta_{km} = c_i b_j$$

$$(AD)_{ij} = \sum_{k=1}^N (A)_{ik} (D)_{kj} = a \sum_{k=1}^N a_k \delta_{kj} = a d_j$$