

Solution to problem # 1

(a)

Observe that $\mathbf{e}_\phi$ and $\mathbf{e}_\theta$ from TS^2 are vector fields along the directions ϕ and θ , resp. To find their coordinates in $\mathbb{R}^3$, one should use Eq. (2.29) from the Altland's book, since we have the mapping $S^2 \mapsto \mathbb{R}^3$. Hence

$$\begin{aligned}\mathbf{e}_\phi &= \partial_\phi(x^1, x^2, x^3) = (-\sin \theta \sin \phi, \sin \theta \cos \phi, 0), \\ \mathbf{e}_\theta &= \partial_\theta(x^1, x^2, x^3) = (\cos \theta \cos \phi, \cos \theta \sin \phi, -\sin \theta).\end{aligned}\tag{1}$$

(b)

In the same fashion as above,

$$\begin{aligned}\mathbf{e}_z &= \partial_z(x^1, x^2, x^3) = \left(\frac{1 - \bar{z}^2}{(1 + z\bar{z})^2}, -i \frac{1 + \bar{z}^2}{(1 + z\bar{z})^2}, \frac{2\bar{z}}{(1 + z\bar{z})^2} \right) \\ \mathbf{e}_{\bar{z}} &= \partial_{\bar{z}}(x^1, x^2, x^3) = \left(\frac{1 - z^2}{(1 + z\bar{z})^2}, i \frac{1 + z^2}{(1 + z\bar{z})^2}, \frac{2z}{(1 + z\bar{z})^2} \right)\end{aligned}\tag{2}$$

(c) & (d)

One may start by relating spherical and stereographic coordinates using the mapping $z(\mathbf{x}) = (x^1 + ix^2)/(1 - x^3)$ to obtain

$$z(\theta, \phi) = \frac{\sin \theta e^{i\phi}}{1 - \cos \theta} = \cot(\theta/2) e^{i\phi}, \quad \bar{z}(\theta, \phi) = \cot(\theta/2) e^{-i\phi}.\tag{3}$$

The inverse mapping $\mathbb{C} \rightarrow S^2$ is then

$$\phi(z, \bar{z}) = -\frac{i}{2} \ln(z/\bar{z}), \quad \theta(z, \bar{z}) = 2 \operatorname{arccot}(z\bar{z}).\tag{4}$$

Next, by definition, $dz(\mathbf{e}_\phi) = \mathbf{e}_\phi(z) = \partial_\phi z$, and etc. To be more formal, I'm using the material from page 539 of the Altland's book. Hence we may organize the matrix of transformation from stereographic to spherical basis,

$$\begin{pmatrix} \partial_\phi z & \partial_\theta z \\ \partial_\phi \bar{z} & \partial_\theta \bar{z} \end{pmatrix} = \begin{pmatrix} ie^{i\phi} \cot(\frac{\theta}{2}) & \frac{e^{i\phi}}{\cos(\frac{\theta}{2}) - 1} \\ -ie^{-i\phi} \cot(\frac{\theta}{2}) & \frac{e^{-i\phi}}{\cos(\frac{\theta}{2}) - 1} \end{pmatrix}\tag{5}$$

For the inverse mapping one gets

$$\begin{pmatrix} \partial_z \phi & \partial_{\bar{z}} \phi \\ \partial_z \theta & \partial_{\bar{z}} \theta \end{pmatrix} = \begin{pmatrix} -\frac{1}{2} ie^{-i\phi} \tan(\frac{\theta}{2}) & \frac{1}{2} ie^{i\phi} \tan(\frac{\theta}{2}) \\ \frac{1}{2} e^{-i\phi} (\cos(\theta) - 1) & \frac{1}{2} e^{i\phi} (\cos(\theta) - 1) \end{pmatrix}\tag{6}$$

Finally, one checks that matrices (5) and (6) are inverse to each other, as it should be.