

Non-abelian gauge fields

• Dirac Lagrangian

① $\mathcal{L} = \bar{\psi} i \gamma^\mu (\partial_\mu + ie A_\mu) \psi ; \quad \bar{\psi} = \psi^\dagger \gamma^0$

$\{\gamma^\mu, \gamma^\nu\} = 2\eta^{\mu\nu} \rightarrow$ form Clifford algebra
 $\mu = 0, 1, \dots, d-1$ & imaginary time $d=4$

② $\nabla_\mu \psi = \partial_\mu \psi + ie A_\mu \psi \rightarrow$ covariant derivative

③ $\mathcal{L}$ is gauge invariant:

Let $\psi' = e^{i\chi} \psi ; \quad A'_\mu = A_\mu - \frac{1}{e} \partial_\mu \chi$; $\chi(x) \in \mathbb{R}$ (real)
then $\mathcal{L}[\psi', A'] = \mathcal{L}[\psi, A]$

• Quantum electrodynamics (abelian $U(1)$ gauge theory)

Action: $S = \int d^4x \mathcal{L} - \frac{1}{4} \int d^4x F_{\mu\nu} F^{\mu\nu}$

$F_{\mu\nu} = \partial_\mu A_\nu - \partial_\nu A_\mu \rightarrow$ e.m. field tensor.

I Geometry of Yang-Mills fields

Given: $\psi = \begin{pmatrix} \psi_1 \\ \vdots \\ \psi_n \end{pmatrix} \rightarrow$ n-component spinor field
(jargon: it has colour / flavour)

• Q: how to use colour structure to define gauge structure? $U(1)$ phase $\rightarrow$ too small

• A: Consider n-dimensional representation of non-Abelian Lie algebra $\mathfrak{g}$ in the colour space.

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(A) Basics of Lie groups & algebras

- $G = SU(2) \rightarrow$ simplest example

$$G = \{ g = \exp \left[\frac{i}{2} \alpha^a \hat{T}_a \right] \mid \alpha^a \in \mathbb{R} \} \quad ; \quad a=1,2,3$$

$$\left[\frac{i}{2} \hat{T}_a, \frac{i}{2} \hat{T}_b \right] = \frac{i}{2} \epsilon_{abc} \hat{T}_c \quad ; \quad T_a \rightarrow \text{Pauli matrices}$$

$$\dim G = 3 \quad , \quad n = 2$$

- General case: let G be compact (semi-simple) Lie group
 $\mathfrak{g} \rightarrow$ its algebra, $\dim(\mathfrak{g}) = k$

(a) Def: (i) The set $\{ \hat{T}_a = \hat{T}^a, a = 1, \dots, k \}$
is basis of $\mathfrak{g}$

(ii) $(\hat{T}_a)^{n \times n} \rightarrow$ Hermitian matrix, $n \rightarrow$ defines representation

(iii) $[\hat{T}_a, \hat{T}_b] = i f_{abc} \hat{T}_c \rightarrow$ commutation relations
 $f_{abc} \rightarrow$ "structure constants" (do not vary with n)

(iv) $\hat{T}_a$ obey Jacobi identity

$$[[T_a, T_b], T_c] + [[T_b, T_c], T_a] + [[T_c, T_a], T_b] = 0$$

(b) Lie group

$$G = \left\{ g = \exp \left[i \sum_{a=1}^k \alpha^a \hat{T}_a \right] \mid \alpha^a \in \mathbb{R} \right\}$$

i.e. exponentiation of algebra

- Set $\{\alpha^a\}$ parametrizes all possible g .

③ Yang-Mills construction:

$$\rightarrow S^\dagger = S^{-1}$$

① $\mathcal{L} = \bar{\psi} i \gamma^\mu \partial_\mu \psi$, $\psi' = \hat{S} \psi$, $\hat{S} \in G \subset U(n)$
 $\Rightarrow$ make it local ! $\downarrow$
global symmetry

② (i) $\psi' = \hat{S}(x) \psi$ with $\hat{S}(x) = \exp[i\alpha^a(x) \hat{T}_a]$.

(ii) Gauge field: $\hat{A}_\mu(x) = A_\mu^a(x) \hat{T}_a \in \mathfrak{g}$
 $\downarrow$
takes values on Lie algebra

(iii) Covariant derivative is defined by

$$\nabla_\mu \psi \equiv \partial_\mu \psi - ig \hat{A}_\mu \psi \quad | \quad g \rightarrow \text{coupling const.}$$

(iv) Under gauge transform $\hat{A}_\mu$ changes as

$$A_\mu' = S A_\mu S^{-1} - \frac{i}{g} (\partial_\mu S) S^{-1} \quad (1)$$

③ Lemma: $\nabla_\mu' \psi' = S(x) \nabla_\mu \psi$

Proof:

$$\begin{aligned} \nabla_\mu' \psi' &= (\partial_\mu - ig A_\mu') S \psi = S (\partial_\mu - ig S^{-1} A_\mu' S + S^{-1} \partial_\mu S) \psi \\ &= S (\partial_\mu - ig A_\mu) \psi \end{aligned}$$

$\Rightarrow$ we have to demand that

$$-ig A_\mu = -ig S^{-1} A_\mu' S + S^{-1} \partial_\mu S \Rightarrow (1) \quad \square$$

④ Result: $\mathcal{L} = \bar{\psi} i \gamma^\mu \nabla_\mu \psi \rightarrow$ gauge inv. Lagrangian

$$\mathcal{L}[\psi, A_\mu] = \mathcal{L}[\psi', A_\mu']$$

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(e) Field strength tensor: $F_{\mu\nu}$ non-Abelian
↑ part

Def: $F_{\mu\nu} = \frac{i}{g} [\hat{D}_\mu, \hat{D}_\nu] = \partial_\mu A_\nu - \partial_\nu A_\mu - ig [A_\mu, A_\nu]$.

$F_{\mu\nu} \in \mathfrak{g} \rightarrow$ belongs to Lie algebra

If one writes $F_{\mu\nu} = \frac{1}{2} F_{\mu\nu}^a \hat{T}_a \Rightarrow$

$$F_{\mu\nu}^a = \partial_\mu A_\nu^a - \partial_\nu A_\mu^a + g f^{abc} A_\mu^b A_\nu^c$$

Lemma: $F_{\mu\nu}' = S F_{\mu\nu} S^{-1}$, since $\hat{D}_\mu' = S \hat{D}_\mu S^{-1}$
↑
simple trans. law!

(f) Yang-Mills Lagrangian:

$$\mathcal{L}_{YM} = \bar{\psi} i \gamma^\mu \nabla_\mu \psi - \frac{1}{8} \text{tr} (F_{\mu\nu} F_{\mu\nu})$$

Note: one usually chooses the basis $\hat{T}_a$ such that

$$\text{tr} (\hat{T}_a \hat{T}_b) = 2 \delta^{ab} \text{ ("orthogonal basis")}$$

$$\Rightarrow \frac{1}{8} \text{tr} (F_{\mu\nu} F_{\mu\nu}) = \frac{1}{4} \sum_{a=1}^k F_{\mu\nu}^a F_{\mu\nu}^a$$

↓
gauge inv. construction $\Rightarrow$

$\mathcal{L}_{YM}$ is locally gauge inv. model!

(g) Phys. applications:

(a) "Chromodynamics": $G = SU(3)$

(b) Weinberg-Salam model of electroweak interactions:
 $G = SU(2) \otimes U(1)$

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③ Language of 1 & 2-forms: (diff. geometry).

1. $A = A_\mu dx^\mu \rightarrow$ 1-form on $\mathbb{R}^d$

2. $F = \frac{1}{2} F_{\mu\nu} dx^\mu \wedge dx^\nu \rightarrow$ 2-form.

3. Lemma: $F \equiv dA - ig A \wedge A$

Proof: $dA = \partial_\nu A_\mu dx^\nu \wedge dx^\mu = \frac{1}{2} (\partial_\mu A_\nu - \partial_\nu A_\mu) dx^\mu \wedge dx^\nu$
 $\uparrow$
 antisymmetrize! $\times dx^\mu \wedge dx^\nu$
 $-ig A \wedge A = -ig A_\mu A_\nu dx^\mu \wedge dx^\nu =$
 $= -\frac{ig}{2} [A_\mu, A_\nu] dx^\mu \wedge dx^\nu \quad \square$

4. Bianchi identity:

exercise(!)

① $D F := dF - ig [A, F] = 0 \quad (2)$

here $[A, F] \equiv A \wedge F - F \wedge A$

② In the coordinate language it has the form:

$D_\mu F_{\lambda\rho} + D_\lambda F_{\rho\mu} + D_\rho F_{\mu\lambda} = 0, \quad (3)$
 $\leftarrow \mu \neq \lambda \neq \rho$

where $D_\mu F_{\lambda\rho} := \partial_\mu F_{\lambda\rho} - ig [A_\mu, F_{\lambda\rho}]$

③ Define dual field tensor:

$*F_{\mu\nu} = \frac{1}{2} \epsilon_{\mu\nu\lambda\rho} F^{\lambda\rho} \Rightarrow$

$\downarrow$
 commutator in Lie algebra

another form of
 (2) & (3).

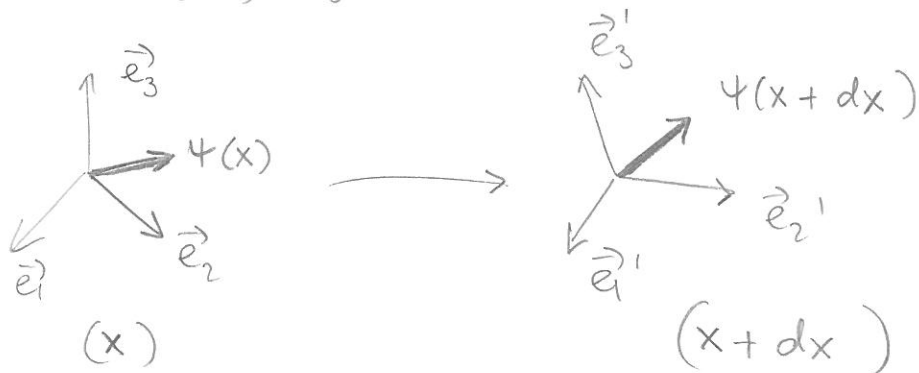
$D_\mu *F^{\mu\nu} = \partial_\mu *F^{\mu\nu} - ig [A_\mu, *F^{\mu\nu}] = 0 \quad \uparrow$

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(D) Geometrical meaning of vector potential A_μ

$$\psi(x) = \psi^k(x) \vec{e}_k(x), \text{ where}$$

$\{ \vec{e}_k^{(x)} \mid k=1, \dots, n \} \rightarrow$ local basis in colour space.



$$d\psi(x) = d\psi^k(x) \vec{e}_k(x) + \psi^k(x) d\vec{e}_k(x)$$

Basis $\vec{e}_k(x)$ may rotate from point to point

$$\text{Let us set } d\vec{e}_k(x) = ig \vec{e}_e A_{k,\mu}^e dx^\mu$$

Matrix $\hat{A}_\mu$ with elements $(\hat{A}_\mu)^e_k \equiv A_{k,\mu}^e$ defines the connection $\Rightarrow$ specifies basis' rotations.

We define

$$\begin{aligned} \delta\psi &:= \psi^k(x) d\vec{e}_k(x) = ig (A_{k,\mu}^e \psi^k \vec{e}_e) dx^\mu = \\ &= (\delta\psi)_\mu dx^\mu, \text{ where } (\delta\psi)_\mu = ig \hat{A}_\mu \psi \end{aligned}$$

Covariant derivative is defined by

$$D\psi = (\psi + d\psi) - (\psi + \delta\psi) = d\psi - ig \hat{A}_\mu \psi dx^\mu$$

$$\Rightarrow \nabla_\mu \psi = \frac{D\psi}{dx^\mu} = \partial_\mu \psi - ig \hat{A}_\mu \psi. \quad \square$$