

## letzte Vorlesung:

### • Rotation (Wirbelstärke)

$$\text{rot } \vec{A}(\vec{r})$$

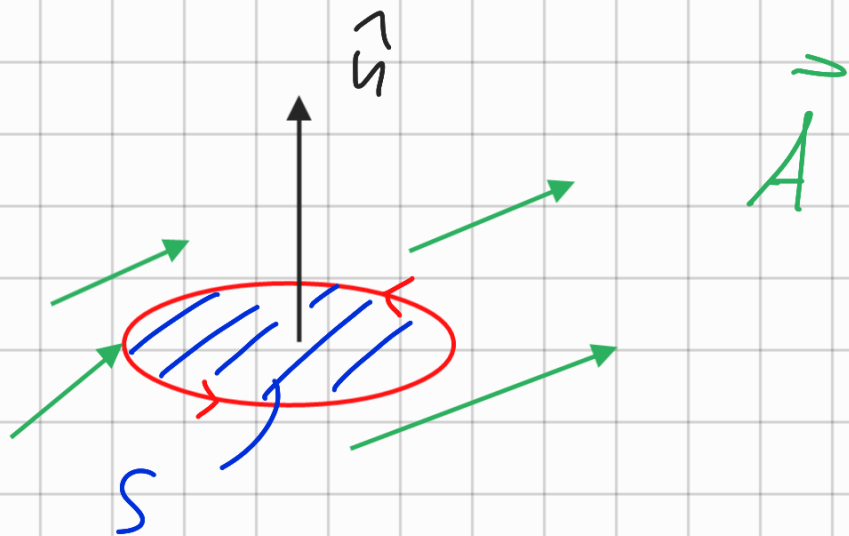
definiert durch

$$\langle \hat{u}, \text{rot } \vec{A}(\vec{r}) \rangle = \lim_{|S| \rightarrow 0} \frac{1}{|S|} \int_{\partial S} \vec{A} d\vec{\ell}$$

$S$ : Fläche bei  $\vec{r}$ ,  $\perp \hat{u}$

$\partial S$ : Rand von  $S$

$|S|$ : Flächeninhalt von  $S$



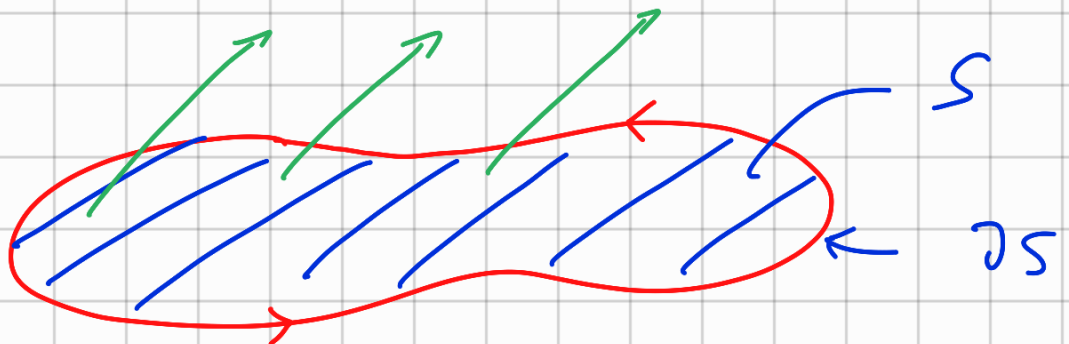
$$\rightarrow \operatorname{rot} \vec{A} = \vec{\nabla} \times \vec{A}$$

$$= \begin{pmatrix} \partial/\partial x_1 \\ \partial/\partial x_2 \\ \partial/\partial x_3 \end{pmatrix} \times \begin{pmatrix} A_1 \\ A_2 \\ A_3 \end{pmatrix}$$

- $\operatorname{rot}(\operatorname{grad} f) = \vec{0}$
- $\operatorname{rot}(f \vec{A})$   
 $= (\operatorname{grad} f) \times \vec{A} + f \operatorname{rot} \vec{A}$

### Satz von Stokes

$$\int_{\partial S} \vec{A} \cdot d\vec{x} = \int_S \operatorname{rot} \vec{A} \cdot d\vec{f}$$



## Magnetostatik:

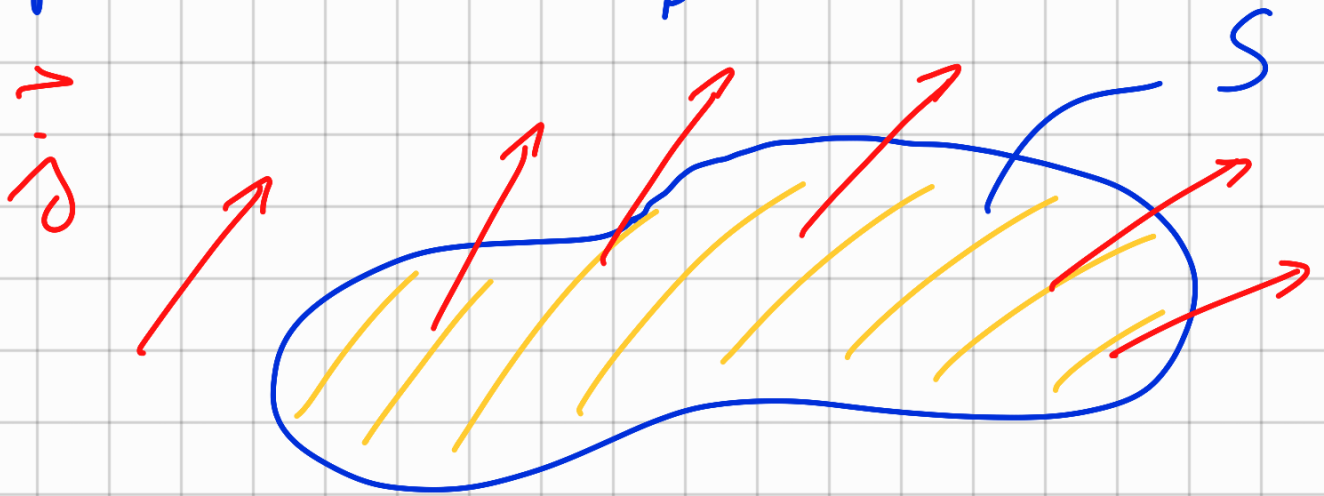
- Ampère:  $\operatorname{rot} \vec{B} = \mu_0 \vec{j}$
- Gauß:  $\operatorname{div} \vec{B} = 0$

## Induktion:

- Faraday:  $\operatorname{rot} \vec{E} = - \frac{\partial \vec{B}}{\partial t}$

integrated Form der Gesetze von

Ampère und Gauß:



$$\underline{\underline{\mu_0 I_S}} = \int_S \mu_0 \vec{j} \cdot d\vec{f} = \int_S \text{rot } \vec{B} \cdot d\vec{f}$$

Ampère

$$= \int_{\partial S} \vec{B} \cdot d\vec{l}$$

Stokes!

Ampère

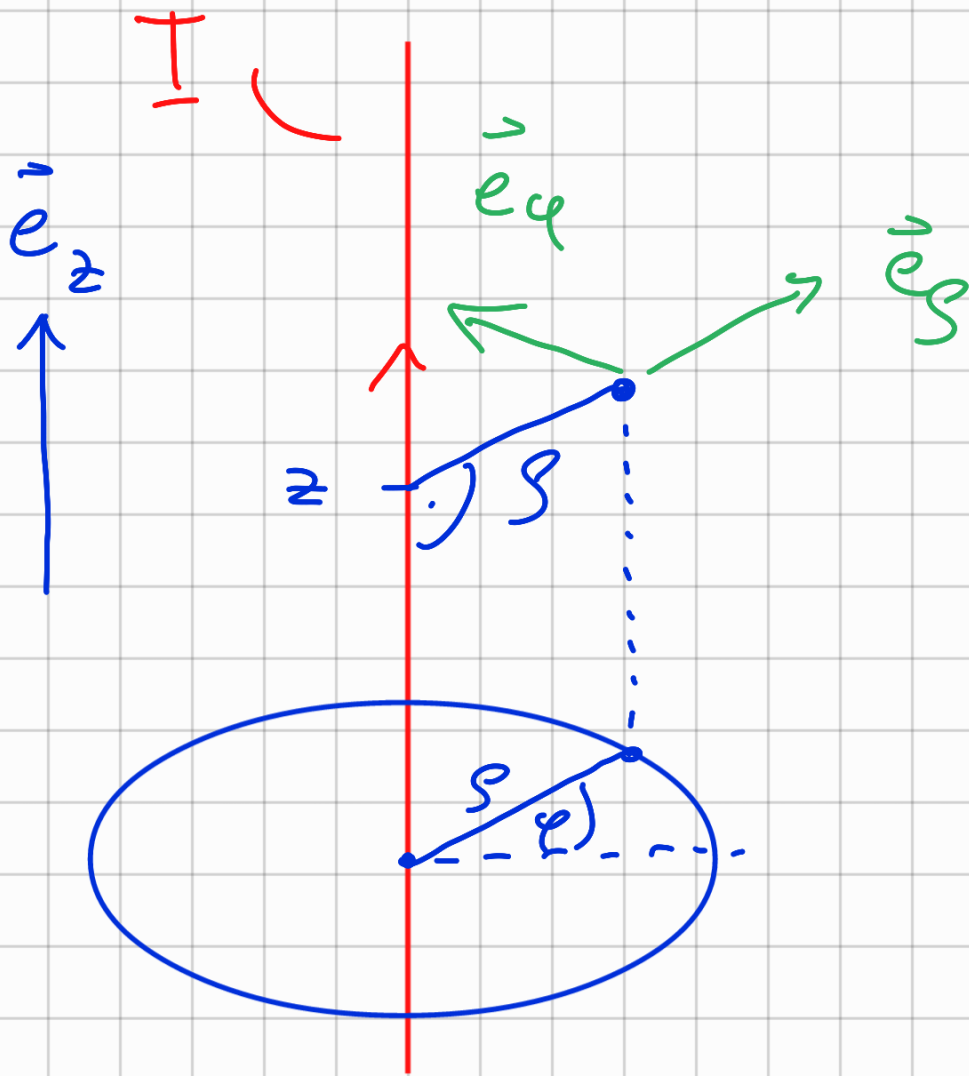
$$\int_{\partial S} \vec{B} \cdot d\vec{l} = \mu_0 I_S$$



$$\int_{\partial V} \vec{B} \cdot d\vec{s} = 0$$

Geoff

Beispiel: Magnetfeld eines  
Strom  $I$  führenden Drahts  
(gerade, unendlich lang)

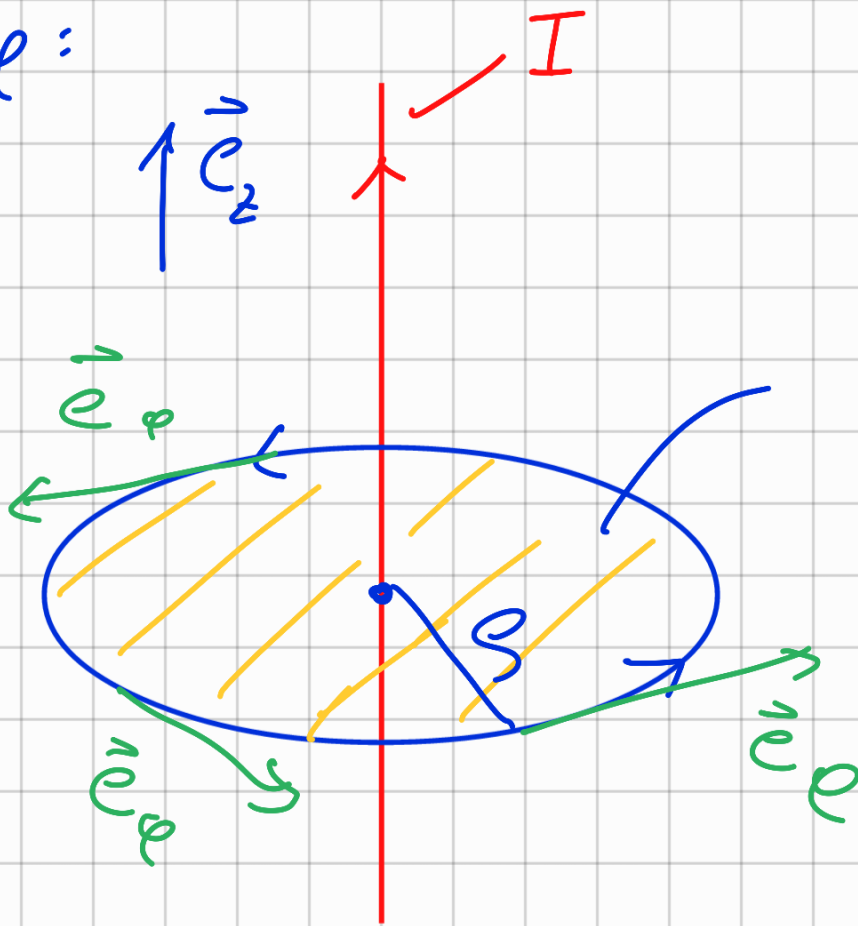


Symmetrie  $\rightarrow$  Ansatz

$$\begin{aligned}
 \vec{B}(s, \varphi, z) = & \underline{B_s(s)} \vec{e}_s \\
 & + \underline{B_\varphi(s)} \vec{e}_\varphi \\
 & + \underline{B_z(s)} \vec{e}_z
 \end{aligned}$$

Bestimmung von  $B_s$ ,  $B_\varphi$ ,  $B_z$  :

$B_\varphi$  :



$B_\varphi(s)$  !

$$s = R_s$$

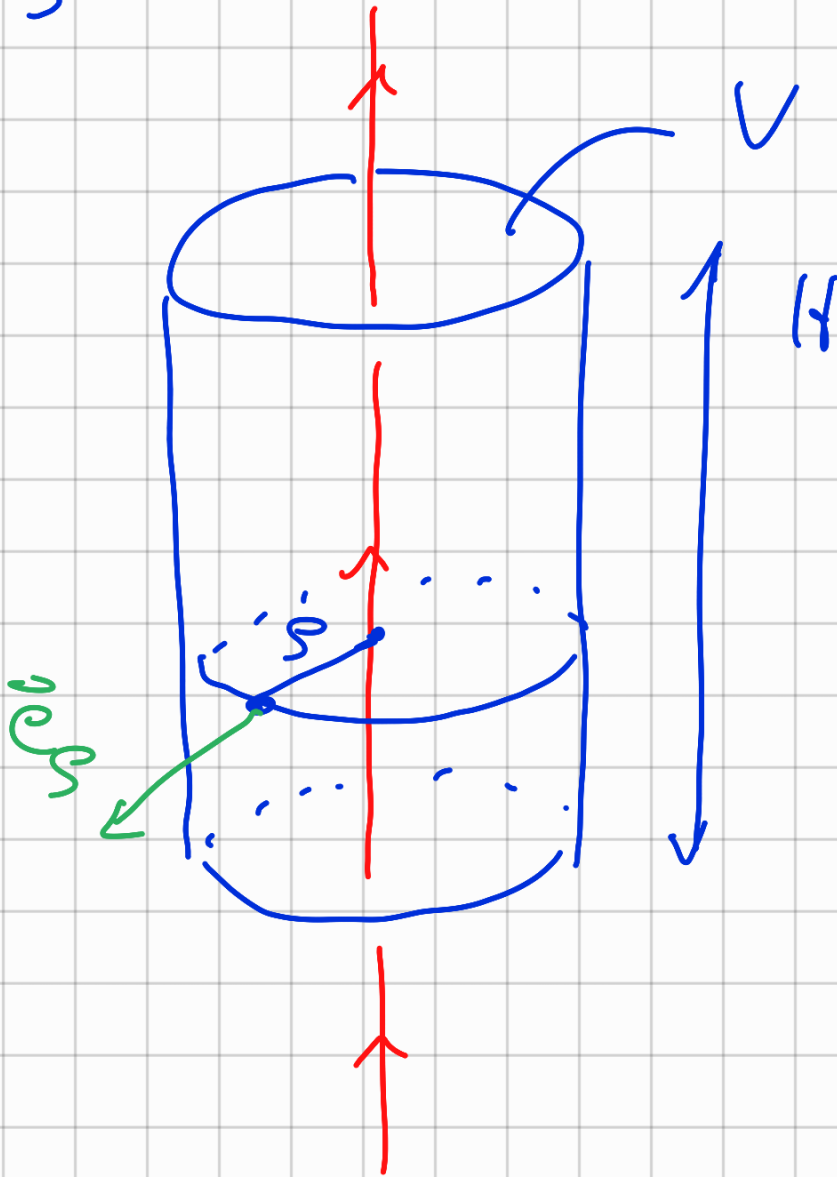
Ampère :

$$\underline{\mu_0 I} = \int_{\partial S} \vec{B} d\vec{\ell} = \underline{2\pi s} \underline{B_\varphi(s)}$$

$$\rightarrow B_\varphi(s) = \frac{\mu_0 I}{2\pi} \cdot \frac{1}{s}$$

$B_S(s) ?$

Gauß:



$$0 = \int_{\partial V} \vec{B} \cdot d\vec{f} = \underbrace{2\pi s H}_{\neq 0} \underline{\underline{B_S(s)}}$$

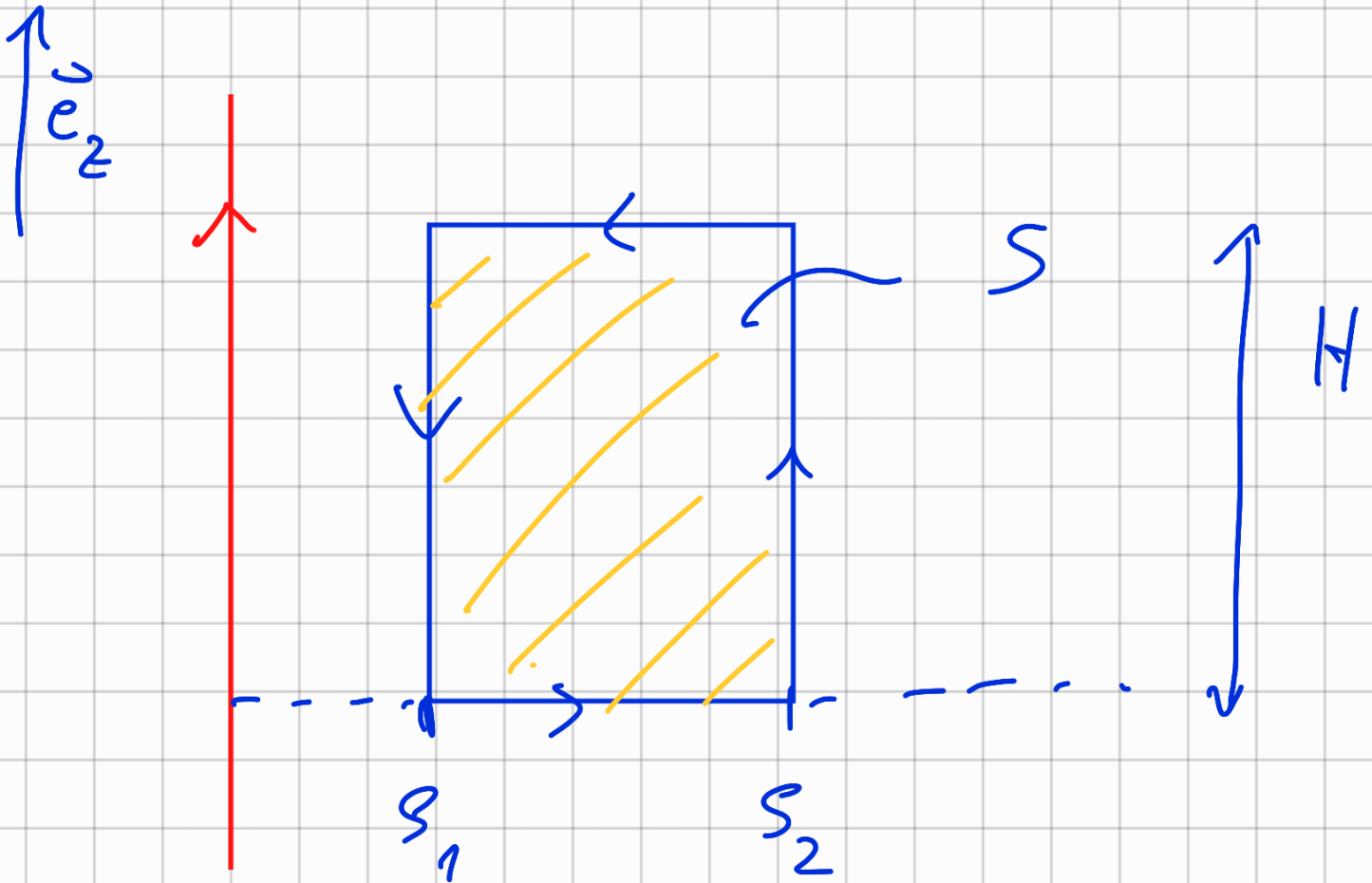
Gauß

$$B_S(s) = 0$$



$B_2(s) :$

ampère :



$$0 = \mu_0 I_S = \int_{\partial S} \vec{B} \cdot d\vec{\ell}$$

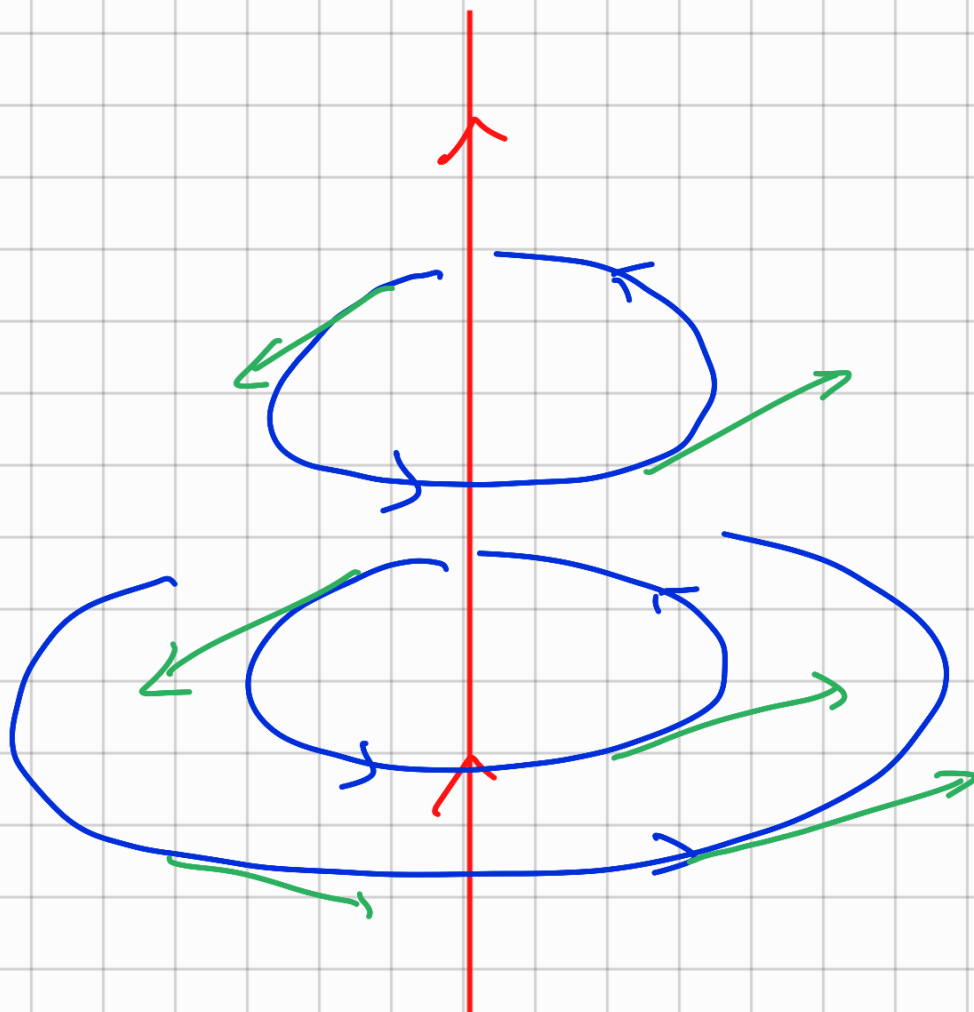
$$0 = H ( B_2(s_2) - B_2(s_1) )$$

$$\rightarrow B_2(s) = \text{const!}$$

→ falls  $\vec{B} \rightarrow 0$  für  $s \rightarrow \infty$

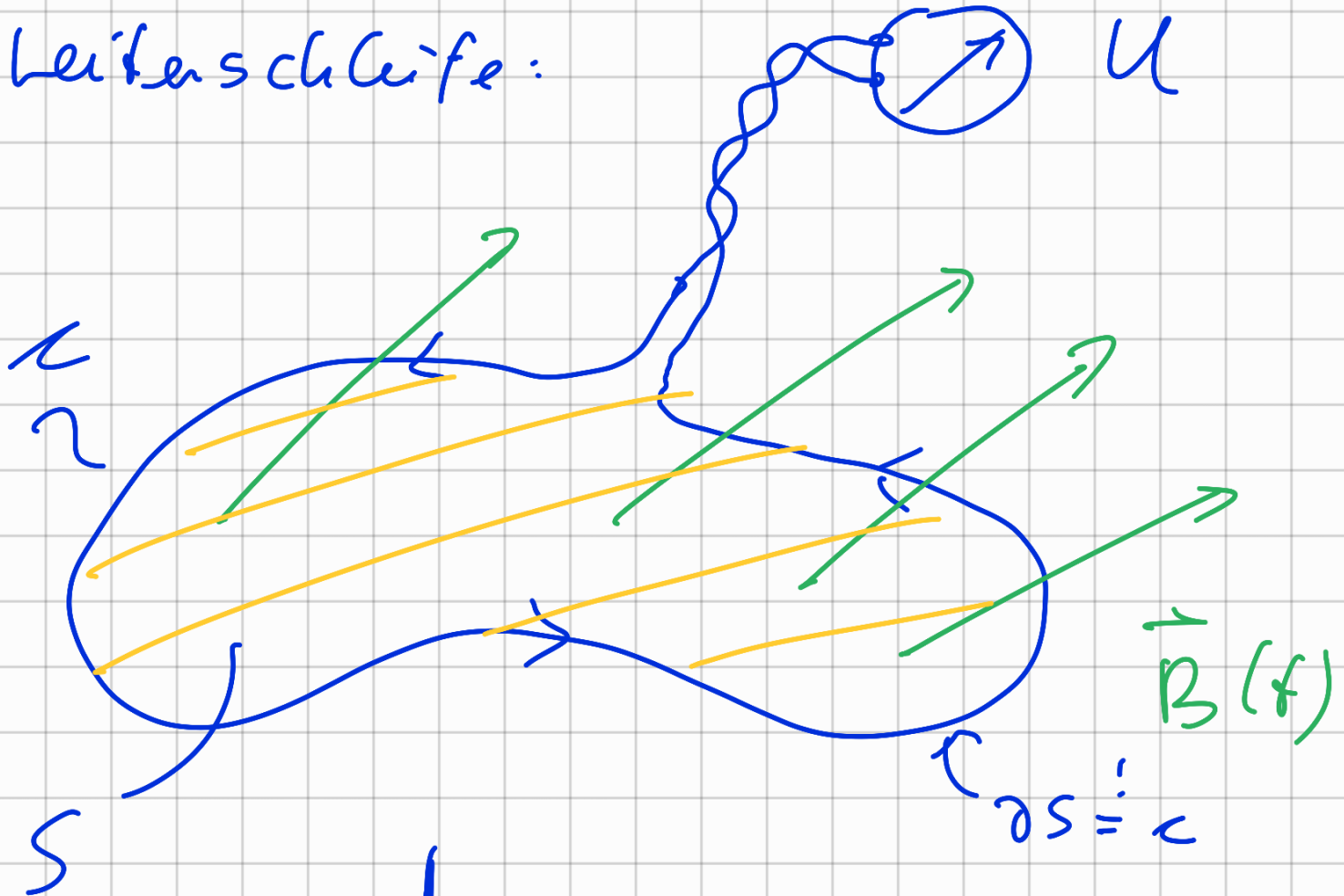
$$B_z(s) = 0$$

$$\vec{B}(\vec{r}) = \frac{\mu_0 I}{2\pi} \frac{1}{s} \vec{e}_\varphi$$



# Induktion:

Leiterschleife:



$$\underline{?} = U \stackrel{!}{=} \int_{\kappa} \vec{E} \cdot d\vec{l}$$

$$= \int_{\partial S} \vec{E} \cdot d\vec{l} \stackrel{\text{Stokes}}{=} \int_S \underline{\text{rot } \vec{E}} \cdot d\vec{f}$$

$$\vec{E} = - \int_S \frac{\partial \vec{B}}{\partial t} d\vec{f}$$

Faraday:

$$\text{rot } \vec{E} = - \frac{\partial \vec{B}}{\partial t}$$

$$= - \frac{d}{dt} \int_S \vec{B}(t) d\vec{f}$$

mag. Fluss durch Fl. S:

$$\underline{\underline{\Phi_S}} = \int_S \vec{B} d\vec{f}$$

↪

$$U = - \frac{d}{dt} \Phi$$