

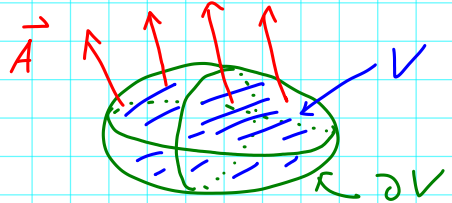
Wiederholung: Divergenz (Quellstärke) eines Vfs:

$$\operatorname{div} \vec{A} = \lim_{|V| \rightarrow 0} \frac{1}{|V|} \int_{\partial V} \vec{A} \cdot d\vec{f}$$

$$= \frac{\partial A_1}{\partial x_1} + \frac{\partial A_2}{\partial x_2} + \frac{\partial A_3}{\partial x_3} \quad (= \vec{\nabla} \cdot \vec{A})$$



Satz von Gauß

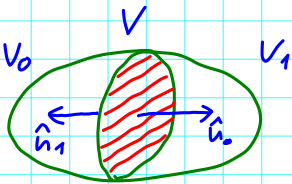


$$\int_{\partial V} \vec{A} \cdot d\vec{f} = \int_V \operatorname{div} \vec{A} \, dV$$

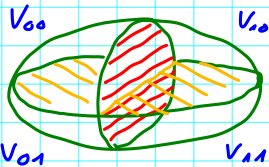
↑
Fluss von $\vec{A}$
durch ∂V

↑
Gesamtquellstärke
von $\vec{A}$ in V

"Physikerbeweis":

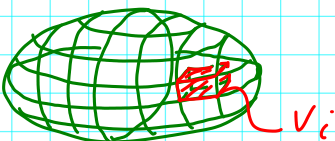


$$\int_{\partial V} \vec{A} \cdot d\vec{f} \stackrel{!}{=} \int_{\partial V_0} \vec{A} \cdot d\vec{f} + \int_{\partial V_1} \vec{A} \cdot d\vec{f}$$



$$\stackrel{!}{=} \int_{\partial V_{00}} \vec{A} \cdot d\vec{f} + \int_{\partial V_{01}} \vec{A} \cdot d\vec{f} + \int_{\partial V_{10}} \vec{A} \cdot d\vec{f} + \int_{\partial V_{11}} \vec{A} \cdot d\vec{f}$$

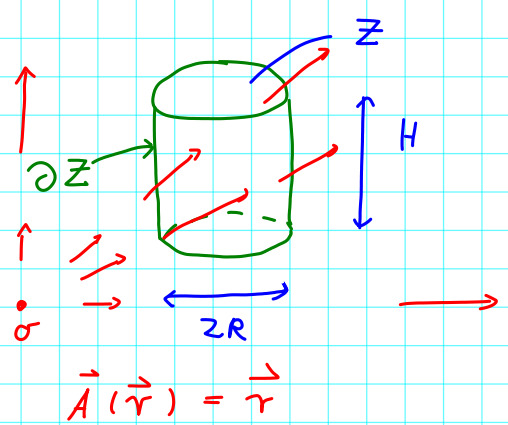
⋮



$$= \sum_i \underbrace{\frac{1}{|V_i|} \int_{\partial V_i} \vec{A} \cdot d\vec{f}}_{\operatorname{div} \vec{A}} \underbrace{|V_i|}_{dV}$$

$|V_i| \rightarrow 0$

Anwendungsbeispiel



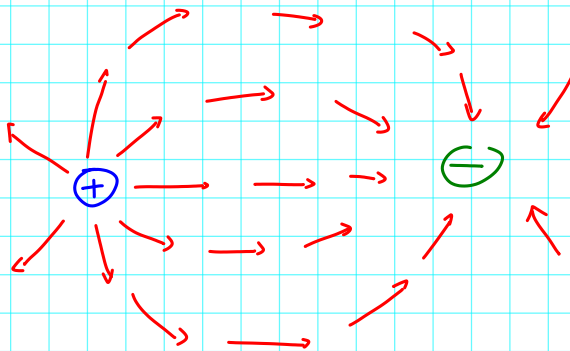
Gauß

$$\int_{\partial Z} \vec{A} \cdot d\vec{f} = \int_Z \underline{\underline{\text{div } \vec{A}}} \, dV = 3 \int_Z dV = 3\pi R^2 H$$

$\uparrow$
 $\text{div } \vec{r} = 3$

Elektrostatik:

„elektrische Ladungen sind Quellen des elektrischen Felds“

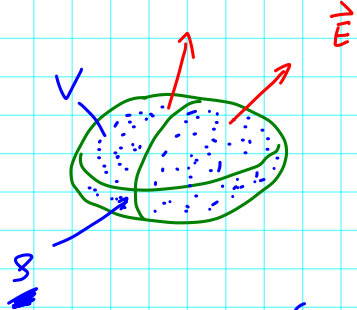


$$\text{div } \vec{E} = \rho / \epsilon_0$$

$\uparrow$
Gaußsches Gesetz

?

2) $\vec{E}(\vec{r})$?



$$\rho/\epsilon_0 = \text{div } \vec{E}$$

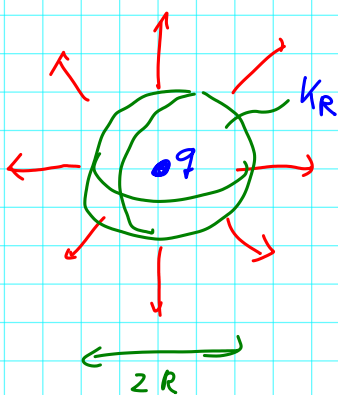
$$Q_V = \int_V \rho \, dV = \epsilon_0 \int_V \underbrace{\text{div } \vec{E}}_{\substack{\uparrow \\ \text{s.v.G.}}} \, dV = \epsilon_0 \int_{\partial V} \vec{E} \cdot d\vec{f}$$

d.h.

$$\boxed{\int_{\partial V} \vec{E} \cdot d\vec{f} = \frac{1}{\epsilon_0} Q_V} \quad ! \quad (*)$$

↑
Gaußsches Gesetz in integraler Form

Γ Bsp.: Elekt. Feld einer Platte q in σ : ?



Ausatz: $\vec{E}(\vec{r}) = E(r) \hat{r}$

$$\underline{q} = Q_R \stackrel{(*)}{=} \epsilon_0 \int_{\partial K_R} \vec{E} \cdot d\vec{f}$$

$$= \epsilon_0 E(R) \underbrace{\int_{S_R} |d\vec{f}|}_{\text{"}4\pi R^2\text{"}} = 4\pi R^2 \epsilon_0 E(R)$$

$$\rightarrow E(R) = \frac{q}{4\pi\epsilon_0} \cdot \frac{1}{R^2}$$

$$\hookrightarrow \vec{E}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \hat{r}$$

$$\vec{r} \neq 0: \rho/\epsilon_0 = \text{div } \vec{E} = \frac{1}{4\pi\epsilon_0} q \underbrace{\text{div } \frac{\hat{r}}{r^2}}_{=0!} = 0!$$

Γ Newtonsche Gravitation:

$$\boxed{\text{div } \vec{G} = -4\pi\gamma \rho_m}$$

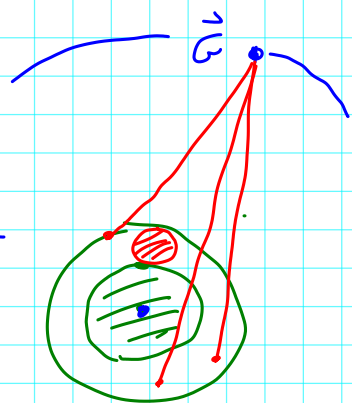
Gravitationsfeld

Massendichte

γ : Grav.konstante

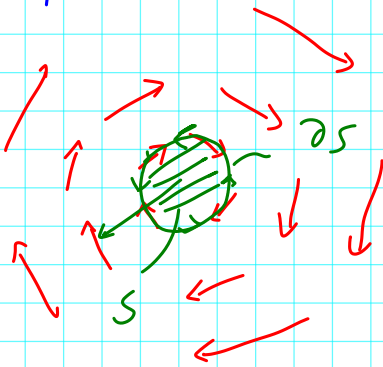
↑
s.v. Gauß

$$\boxed{\int_{\partial V} \vec{G} \cdot d\vec{f} = -4\pi\gamma M_V}$$



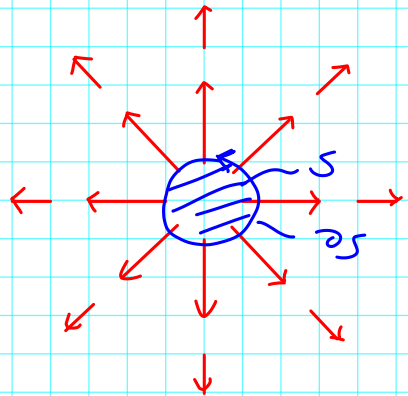
Rotation (Wirbelstärke) eines Vfs, Satz von Stokes

Vf. $\vec{A}$:



$$\int_{\partial S} \vec{A} d\vec{\ell} \neq 0!$$

Vf. $\vec{B}$:



$$\int_{\partial S} \vec{B} d\vec{\ell} = 0$$

Def.: Rotation (Wirbelstärke) des Vfs. $\vec{A}$ im Punkt $\vec{r}_0$

$:=$ Vektor $\text{rot } \vec{A}(\vec{r}_0)$ bestimmt durch:

$$\langle \hat{n}, \text{rot } \vec{A}(\vec{r}_0) \rangle := \lim_{|S| \rightarrow 0} \frac{1}{|S|} \int_{\partial S} \vec{A} d\vec{\ell}$$

wobei:

S : Flächenelement

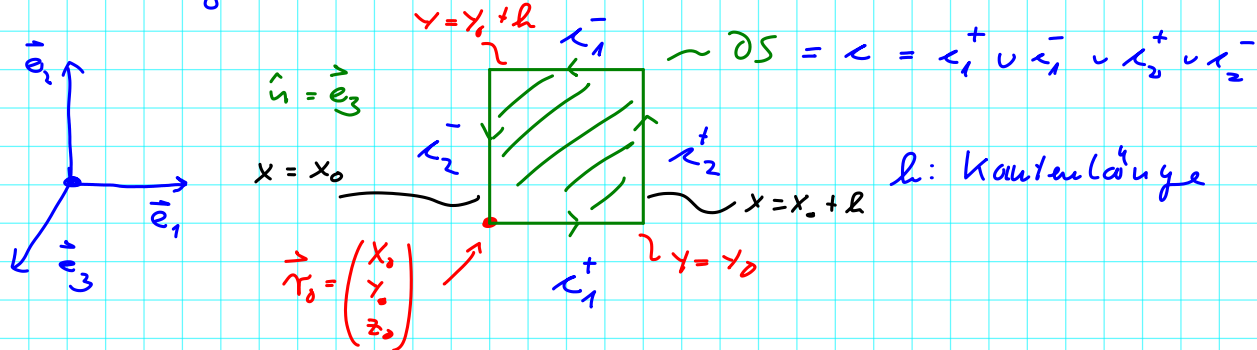
$\hat{n}$: Flächennormale

$|S|$: Flächeninhalt

∂S : Rand der Fläche



Berechnung der Rotation in kart. Koordinaten:



$$\int_{\kappa=\partial S} \vec{A} d\vec{l} = I_1 + I_2,$$

$$\text{mit } I_1 = \int_{\kappa_1^+ \cup \kappa_1^-} \vec{A} d\vec{l} = \int_{x_0}^{x_0+l} \{A_1(x, y_0, z_0) - A_1(x, y_0+l, z_0)\} dx$$

$$\leadsto I_1 = -l^2 \frac{\partial A_1}{\partial x_2}(\vec{r}_0) = -l \frac{\partial A_1}{\partial x_2}(\vec{r}_0)$$

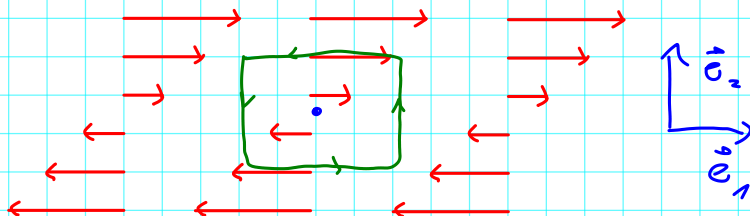
$$\text{analog: } I_2 = + \frac{\partial A_2}{\partial x_1}(\vec{r}_0) l^2$$

$$\begin{aligned} (\text{rot } \vec{A}(\vec{r}_0))_3 &= \langle \vec{e}_3, \text{rot } \vec{A}(\vec{r}_0) \rangle = \lim_{h \rightarrow 0} \frac{1}{h} \left(h \frac{\partial A_2}{\partial x_1}(\vec{r}_0) - h \frac{\partial A_1}{\partial x_2}(\vec{r}_0) \right) \\ &= \frac{\partial A_2}{\partial x_1} - \frac{\partial A_1}{\partial x_2} = (\vec{\nabla} \times \vec{A})_3 \end{aligned}$$

$$\text{rot } \vec{A} = \begin{pmatrix} \frac{\partial A_3}{\partial x_2} - \frac{\partial A_2}{\partial x_3} \\ \frac{\partial A_1}{\partial x_3} - \frac{\partial A_3}{\partial x_1} \\ \frac{\partial A_2}{\partial x_1} - \frac{\partial A_1}{\partial x_2} \end{pmatrix} = \vec{\nabla} \times \vec{A}$$

Bsp.:

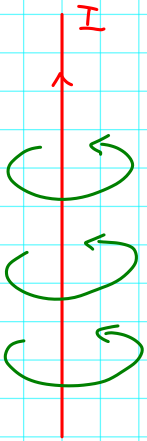
$$\vec{j}(\vec{r}) = x_2 \vec{e}_1 = \begin{pmatrix} x_2 \\ 0 \\ 0 \end{pmatrix}$$



$$\text{rot } \vec{j}(\vec{r}) = \begin{pmatrix} \partial/\partial x_1 \\ \partial/\partial x_2 \\ \partial/\partial x_3 \end{pmatrix} \times \begin{pmatrix} x_2 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix}$$

Anwendungen:

1) Magnetostatik: "elektrische Ströme erzeugen magnetische Wirbelfelder"



$$\text{rot } \vec{B} = \mu_0 \vec{j}$$

↑ elektr. Stromdichte

Ampère - Gesetz

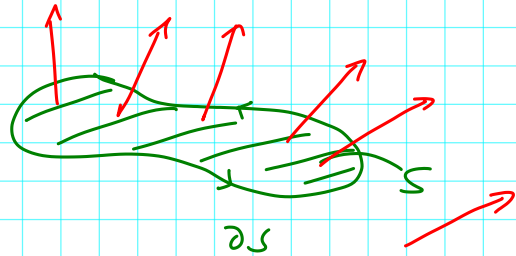
2) Faradaysche Induktionsgesetz:

"zeitlich veränderliches Magnetfeld induziert ein elektr. Wirbelfeld"



$$\text{rot } \vec{E} = - \frac{\dot{\vec{B}}}{}$$

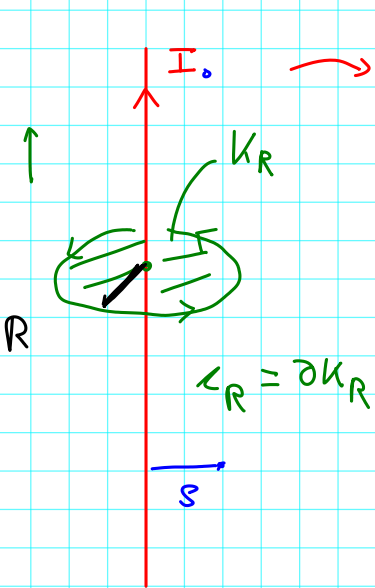
Satz von Stokes



$$\int_{\partial S} \vec{A} d\vec{l} = \int_S \text{rot } \vec{A} d\vec{f}$$

Anwendungsbeispiel

$$\text{rot } \vec{B} = \mu_0 \vec{j}$$



$$\vec{j} \rightarrow \vec{j}_0 \rightarrow \vec{B}(\vec{r})$$

$$\underline{\underline{I_0 \doteq I_{K_R}}} = \frac{1}{\mu_0} \int_{K_R} \vec{B} \cdot d\vec{\ell} = \frac{1}{\mu_0} B(R) 2\pi R$$

Ansatz: $\vec{B} = B(s) \vec{e}_\varphi$

$$\vec{B} = \frac{I_0}{2\pi\mu_0} \frac{1}{s} \cdot \vec{e}_\varphi$$

$$\vec{j} = \frac{1}{\mu_0} \text{rot } \vec{B}$$



$$I_S = \int_S \vec{j} \cdot d\vec{\ell} = \frac{1}{\mu_0} \int_S \text{rot } \vec{B} \cdot d\vec{\ell}$$

$$= \frac{1}{\mu_0} \int_{\partial S} \vec{B} \cdot d\vec{\ell}$$

Stokes!

$$\int_{\partial S} \vec{B} \cdot d\vec{\ell} = \mu_0 I_S$$