

Letzte Vrs.:

$$\begin{array}{ccc} \text{SO}(3) \ni \mathbf{R} & \longmapsto & \mathcal{U}(\mathbf{R}) \in \mathcal{L}(\mathcal{H}) \\ \vec{r} \mapsto \mathbf{R}\vec{r} & & |\psi\rangle \mapsto \mathcal{U}(\mathbf{R})|\psi\rangle \end{array}$$

S.d.:

- $\mathcal{U}(\mathbf{R})$ unitär

- $\mathcal{U}(\mathbb{1}_3) = \mathbb{1}_{\mathcal{H}}$

- $\mathcal{U}(\mathbf{R}'\mathbf{R}) = \mathcal{U}(\mathbf{R}')\mathcal{U}(\mathbf{R})$

⌈ $\mathbf{R} \mapsto \mathcal{U}(\mathbf{R})$
Darstellung
von $\text{SO}(3)$ ⌋

- $\mathcal{U}_{\text{ort}}(\mathbf{R})|\vec{r}\rangle = |\mathbf{R}\vec{r}\rangle$

→ Drehimpuls

$$\mathcal{J}_e := i\hbar \left. \frac{\partial}{\partial \varphi} \mathcal{U}(\mathbf{R}_{e,\varphi}) \right|_{\varphi=0}$$

→ Vertauschungsrelationen:

$$[\mathcal{J}_k, \mathcal{J}_e] = i\hbar \varepsilon_{k e m} \mathcal{J}_m$$

⌈ ebenso für L_k, S_k
da $\vec{\mathcal{J}} = \vec{L} + \vec{S}$ ⌋

$$\rightarrow \mathcal{U}(\mathbf{R}_{\vec{n},\varphi}) = e^{-i\vec{n} \cdot \vec{\mathcal{J}} \varphi / \hbar} = e^{-i\vec{n} \cdot \vec{L} \varphi / \hbar} \otimes e^{-i\vec{n} \cdot \vec{S} \varphi / \hbar}$$

→ Bahndrehimpuls: $\hat{\vec{L}} = \hat{\vec{r}} \times \hat{\vec{p}}$

Spinoperatoren $\vec{S} = \begin{pmatrix} S_1 \\ S_2 \\ S_3 \end{pmatrix}$

(= Drehimpulsoperatoren des "Eigen Drehimpulses")

• genügen $[S_x, S_y] = i\hbar \epsilon_{lmn} S_m$

• operieren auf $\mathcal{H}_{\text{spin}} = \text{Span} \{ |\uparrow\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, |\downarrow\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \} \cong \mathbb{C}^2$

$\Rightarrow$ d.h. $S_x \in \mathcal{M}(2 \times 2, \mathbb{C})$

$\rightarrow$ $S_x = \frac{\hbar}{2} \sigma_x$

(eindeutig bis auf
unitär äquivalente
Darstellungen, vgl. Üb.)

d.h. $\vec{S} = \frac{\hbar}{2} \vec{\sigma}$ mit $\vec{\sigma} = \begin{pmatrix} \sigma_1 \\ \sigma_2 \\ \sigma_3 \end{pmatrix}$:

	$S_1 = \frac{\hbar}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$	$S_2 = \frac{\hbar}{2} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$	$S_3 = \frac{\hbar}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$
Eigenzust.	$ \chi_{\pm}\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ \pm 1 \end{pmatrix}$	$ \chi_{\pm}\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ \pm i \end{pmatrix}$	$ \uparrow\rangle \equiv z+\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ $ \downarrow\rangle \equiv z-\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$
Eigenwerte:	$\pm \hbar/2$	$\pm \hbar/2$	$\pm \hbar/2$

→ Transformation eines Spinzustandes

$$|\psi\rangle = \alpha |\uparrow\rangle + \beta |\downarrow\rangle = \begin{pmatrix} \alpha \\ \beta \end{pmatrix} \quad (\in \mathbb{C}^2)$$

unter Rotation $R_{\vec{u}, \varphi}$ ($\in \text{SO}(3)$):

$$|\psi\rangle \mapsto |\psi'\rangle = U_{\text{spin}}(R_{\vec{u}, \varphi}) |\psi\rangle \text{ mit}$$

$$U_{\text{spin}}(R_{\vec{u}, \varphi}) = e^{-i \vec{u} \cdot \vec{S} \varphi / \hbar} = e^{-i \vec{u} \cdot \vec{\sigma} \frac{\varphi}{2}}$$

$\vec{S} = \frac{\hbar}{2} \vec{\sigma}$

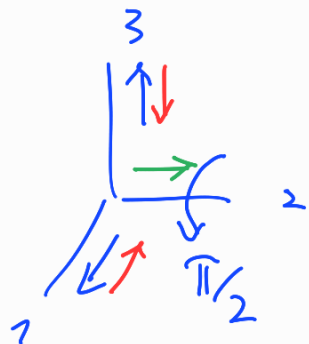
$$\vec{u} \cdot \vec{\sigma} = u_1 \sigma_1 + u_2 \sigma_2 + u_3 \sigma_3 = \begin{pmatrix} u_3 & u_1 - i u_2 \\ u_1 + i u_2 & -u_3 \end{pmatrix}$$

$$\rightarrow (\vec{u} \cdot \vec{\sigma})^2 = \mathbb{I}_2 \quad (|\vec{u}| = 1)$$

$$\rightarrow U_{\text{spin}}(R_{\vec{u}, \varphi}) = \mathbb{I} \cos \frac{\varphi}{2} - i \vec{u} \cdot \vec{\sigma} \sin \frac{\varphi}{2}$$

(Check:

$$U_{2,\pi/2} := U_{\text{sp}}(R_{2,\pi/2}) \quad , \quad -i\sigma_2 = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$



$$= \underbrace{1}_{1/\sqrt{2}} \cos \pi/4 + \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \underbrace{\sin \pi/4}_{1/\sqrt{2}}$$

$$U_{2,\pi/2} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} ;$$

$$\begin{aligned} \bullet \quad U_{2,\pi/2} |z+\rangle &= \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = |x+\rangle \checkmark \\ \text{" " } |z-\rangle &= \text{" " } \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 1 \end{pmatrix} = -|x-\rangle \checkmark \end{aligned}$$

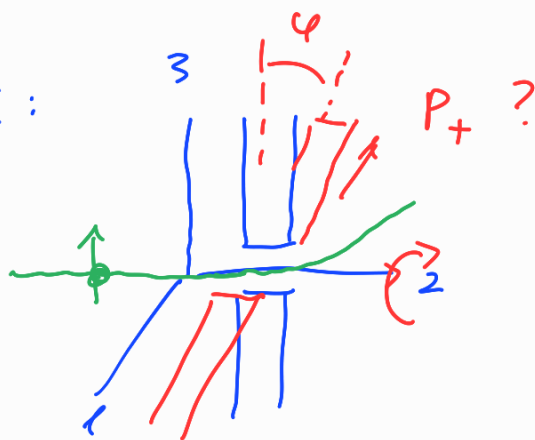
$$\begin{aligned} \bullet \quad U_{2,\pi/2} |x+\rangle &= \frac{1}{2} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix} = |z-\rangle \checkmark \\ \text{" " } |x-\rangle &= \text{" " } \begin{pmatrix} 1 \\ -1 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} = |z+\rangle \checkmark \end{aligned}$$

$$\bullet \quad U_{2,\pi/2} |y+\rangle = \frac{1}{2} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ i \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 1-i \\ 1+i \end{pmatrix}$$

$$= \frac{1-i}{2} \begin{pmatrix} 1 \\ \frac{1+i}{1-i} \end{pmatrix} = e^{-i\pi/4} \underbrace{\frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ i \end{pmatrix}}_{|y+\rangle} \checkmark$$

$$\text{" " } |y-\rangle = \text{" " } = e^{+i\pi/4} |y-\rangle \checkmark$$

Beispiel:



$$|z_+' \rangle = U(P_2 \varphi) |z_+ \rangle$$

$$= \underline{1} \cos \varphi/2 + \underbrace{\begin{pmatrix} 0 & -1 \\ 1 & 1 \end{pmatrix}}_{= -i\sigma_2} \sin \varphi/2 = \begin{pmatrix} \cos \varphi/2 & -\sin \varphi/2 \\ \sin \varphi/2 & \cos \varphi/2 \end{pmatrix}$$



$$P_+ = \left| \langle z_+' | z_+ \rangle \right|^2 = \left| \langle z_+ | U_{2,\varphi} | z_+ \rangle \right|^2$$

$\begin{pmatrix} 1 \\ 0 \end{pmatrix}$

 $\begin{pmatrix} 1 \\ 0 \end{pmatrix}$

$$= |\cos \varphi/2|^2$$

$$\Gamma \quad \varphi = 30^\circ = \pi/6 \quad \rightarrow$$

$$P_+ = |\cos \frac{\pi}{12}|^2$$

$$= 0,93 \quad . \quad \perp$$

Bemerkung: $U(R_{\vec{u}, \varphi}) = \underline{1} \cos \underline{\varphi/2} - i \vec{\sigma} \cdot \vec{u} \sin \underline{\varphi/2}$

2π - Rot.: $U(R_{\vec{u}, 2\pi}) = -\underline{1}$ | $R_{\vec{u}, 2\pi} = \underline{1}$
 $\neq$ $(\parallel)$

4π - Rot.: $U(R_{\vec{u}, 4\pi}) = +1$ | $R_{\vec{u}, 4\pi} = \underline{1}$

($\Rightarrow$ AQM, QFT.)

Drehimpulseigenwerte und -zustände

Ausgangspunkt: $[J_x, J_y] = i\hbar \epsilon_{xyz} J_z$ (*)

$\rightarrow$ allg. Aussagen über Eigenwerte / -zustände:

J^2 und J_z

$\Gamma \quad J^2 = J_1^2 + J_2^2 + J_3^2$

(*) $\rightarrow [J^2, J_x] = \dots = 0 \quad \perp$

insb. $[J^2, J_3] = 0$

$\rightarrow$ gemeinsame Eigenbasis von J^2, J_3 :

Eigenbasis $|a, b\rangle$:

$$J^2 |a, b\rangle = a |a, b\rangle$$

$$J_3 |a, b\rangle = b |a, b\rangle$$

a, b ?

Hilfsvorgang :

$$\begin{aligned} J_+ &:= J_1 + i J_2 \\ J_- &:= J_1 - i J_2 \end{aligned} \quad \begin{array}{c} \nearrow \\ \searrow \end{array} \quad \begin{array}{c} + \\ - \end{array}$$

(*) $\rightarrow$

- $[J_3, J_+] = \hbar J_+$
- $[J_3, J_-] = -\hbar J_-$

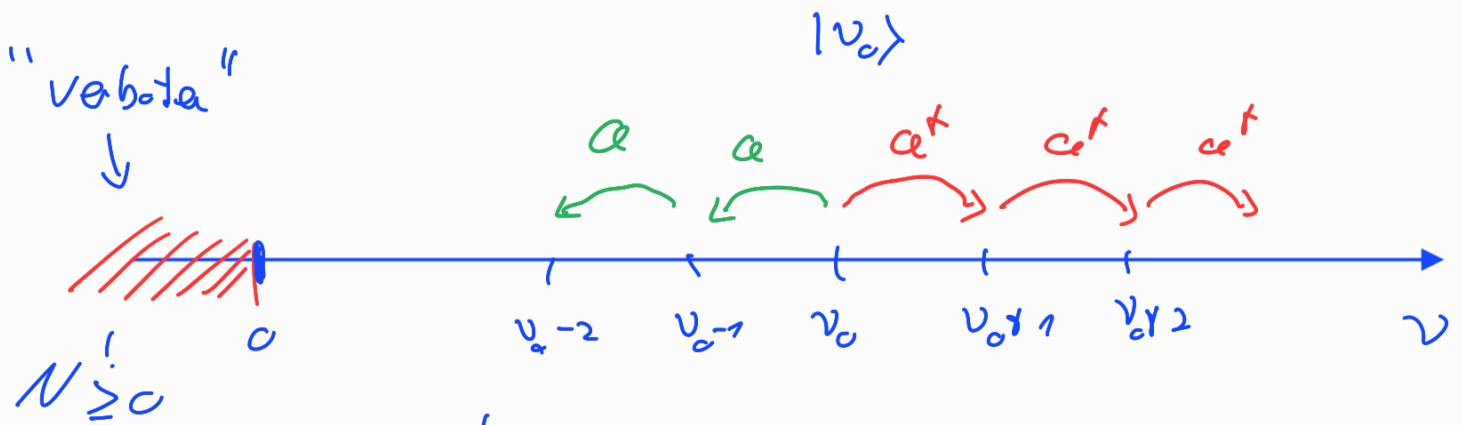
$$([J^2, J_{\pm}] = 0)$$

Erinnerung: harm. Oszill. : a, a^+ , $[a, a^+] = 1$

$$N = \underline{a^+ a} , \quad N |v\rangle = v |v\rangle$$

- $[N, \underline{a^+}] = \underline{a^+}$

- $[N, \underline{a}] = \underline{-a}$

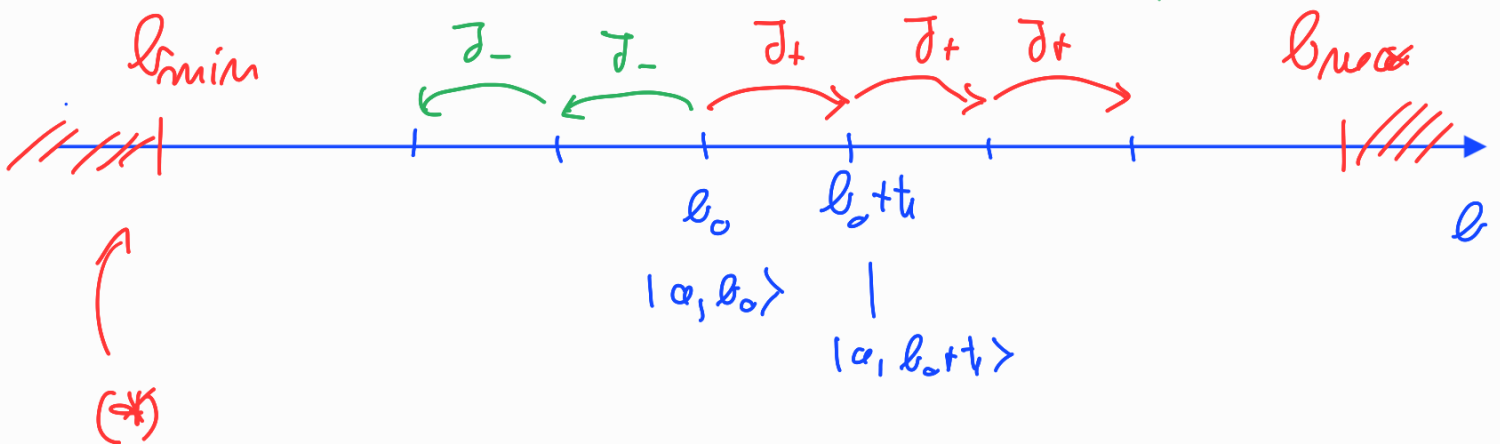


!

$$a|0\rangle = 0 \rightarrow v_c \in \mathbb{N}$$

→ $|v\rangle$, $v = 0, 1, 2, 3, \dots$

mit gleicher Rechnung (aufgrund gleicher Kom.-Relationen):



$$0 \leq J^2 - J_3^2$$

↖

$$\langle J^2 - J_3^2 \rangle_\psi = \langle J_1^2 \rangle_\psi + \langle J_2^2 \rangle_\psi \geq 0!$$

für bel $|\psi\rangle$

↘

→ es d. Zust. $|a, b_{\max}\rangle, |a, b_{\min}\rangle$ s. d.

$$\circ \quad J_+ |a, b_{\max}\rangle = 0 \quad !$$

$$\cdot \quad J_- |a, b_{\min}\rangle = 0 \quad !$$

→ $\underbrace{J_- J_+}_{" } |a, b_{\max}\rangle = 0$

$$(J_1 - i J_2)(J_1 + i J_2) = \overbrace{J_1^2 + J_2^2}^{J^2 - J_3^2} + i \overbrace{[J_1, J_2]}^{i J_3 \cdot \hbar}$$

$$= J^2 - J_3^2 - \hbar J_3$$

$$(\underbrace{J^2}_{\text{grün}} - \underbrace{J_3^2}_{\text{rot}} - \hbar \underbrace{J_3}_{\text{rot}}) | \underbrace{a}_{\text{grün}}, \underbrace{b_{\max}}_{\text{rot}} \rangle = 0$$

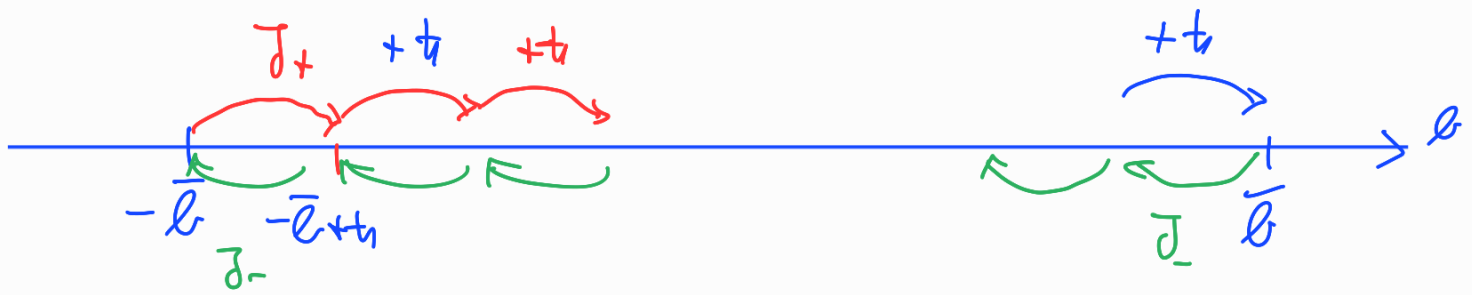
$$(a - b_{\max}^2 - \hbar b_{\max}) |a, b_{\max}\rangle = 0$$

d. h. $\cdot \quad a = b_{\max} (b_{\max} + \hbar)$

analog: $\cdot \quad a = b_{\min} (b_{\min} - \hbar)$

$$\rightarrow b_{\min} = -b_{\max} \equiv -\bar{b}$$

$$b_{\max} =: \bar{b}$$



$$\rightarrow 2\bar{l} = \underline{n}t, \quad n = 0, 1, \dots$$

$$\bar{l} = t \cdot \underline{\frac{n}{2}} = \left(0, \frac{t}{2}, t, \frac{3}{2}t, \dots\right)$$

$$\begin{aligned} \rightarrow a &= \bar{l}(\bar{l} + t) \\ &= t^2 \underline{\frac{n}{2}} \left(\underline{\frac{n}{2}} + 1 \right) \end{aligned}$$

$\rightarrow j$

Drehimpulsquantenzahlen

$$j = 0, \frac{1}{2}, 1, \frac{3}{2}, \dots, \quad j \in \frac{1}{2}\mathbb{N}$$

$$m = -j, -j+1, \dots, j-1, j$$

Drehimpuls eigenzustände

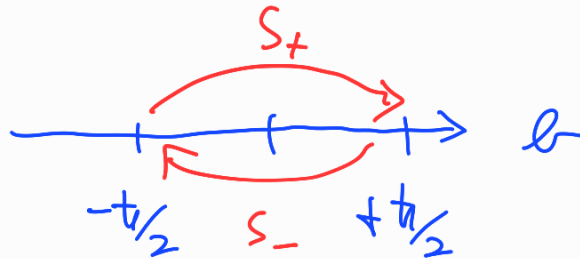
$$|j, m\rangle \quad (|a, b\rangle)$$

$$\underline{J^2} |j, m\rangle = \underline{t^2 j(j+1)} |j, m\rangle, \quad \underline{J_3} |j, m\rangle = \underline{tm} |j, m\rangle$$

Beispiele : Spin des Elektrons :

$$S_z |z\pm\rangle = \pm \frac{\hbar}{2} |z\pm\rangle$$

↪ $m = \pm 1/2$, $j \equiv S = 1/2$!



$$\left(|z+\rangle = \begin{matrix} | \\ s \end{matrix} \begin{matrix} 1/2, \\ m \end{matrix} 1/2 \rangle, |z-\rangle = |1/2, -1/2\rangle \right)$$

$$S_+ = S_1 + i S_2 = \frac{\hbar}{2} (\sigma_1 + i \sigma_2) = \hbar \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$$

$$S_- = S_1 - i S_2 = \hbar \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$$

$\Downarrow$

$$S_+ \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \hbar \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \hbar \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \hbar |\uparrow\rangle$$

$$S_- \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \hbar \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \hbar \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \hbar |\downarrow\rangle$$

$\Uparrow$

$$S_+ \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \hbar \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = 0 !$$

„Elektron ist Spin $1/2$ Teilchen“

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